

Methods of Solving Flag Partial Differential Equations

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Plan of Talk

- 1 Polynomial Solutions
- 2 Evolution Equations
- 3 Constant-Coefficient PDEs

Flag Partial Differential Equations

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A *partial differential equation of flag type* is the linear differential equation of the form:

$$(d_1 + f_1 d_2 + f_2 d_3 + \cdots + f_{n-1} d_n)(u) = 0,$$

where d_1, d_2, \dots, d_n are certain commuting locally nilpotent differential operators on the polynomial algebra $\mathbb{R}[x_1, x_2, \dots, x_n]$ and f_1, \dots, f_{n-1} are polynomials satisfying

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Flag partial differential equations naturally appear in geometry, physics and the representation theory of Lie algebras (groups). Many variable-coefficient (generalized) Laplace equations, wave equations, Klein-Gordon equations, Helmholtz equations are of this type. Solving such equations is also important in finding invariant solutions of nonlinear partial differential equations.

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$$T_1(\mathcal{B}, \mathcal{A}), T_1^-(\mathcal{B}, \mathcal{A}) \subset (\mathcal{B}, \mathcal{A}),$$

$$T_1(\eta_1 \eta_2) = T_1(\eta_1) \eta_2, \quad T_1^-(\eta_1 \eta_2) = T_1^-(\eta_1) \eta_2$$

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Then we have

$$\begin{aligned} & \{g \in \mathcal{A} \mid (T_1 + T_2)(g) = 0\} \\ &= \text{Span}\left\{\sum_{i=0}^{\infty} (-T_1^{-1} T_2)^i (hg) \mid g \in V, h \in \mathcal{B}; T_1(h) = 0\right\}, \end{aligned}$$

where the summation is finite under our assumption. Moreover, the operator $\sum_{i=0}^{\infty} (-T_1^{-1} T_2)^i T_1^{-1}$ is a right inverse of $T_1 + T_2$.

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We remark that the above operator T_1 and T_2 may not commute.

Take the notion

$$\overline{i,j} = \{i, i+1, \dots, j\}$$

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Define

$$x^\alpha = x_1^{\alpha_1} x_2^{\alpha_2} \cdots x_n^{\alpha_n} \text{ for } \alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n.$$

Moreover, we denote

$$\epsilon_i = (0, \dots, 0, \overset{i}{1}, 0, \dots, 0) \in \mathbb{N}^n.$$

For each $i \in \overline{1, n}$, we define the linear operator $\int_{(x_i)}$ on \mathcal{A} by:

$$\int_{(x_i)} (x^\alpha) = \frac{x^{\alpha+\epsilon_i}}{\alpha_i + 1} \text{ for } \alpha \in \mathbb{N}^n.$$

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$$\int_{(x_i)}^{(0)} = 1, \quad \int_{(x_i)}^{(m)} = \overbrace{\int_{(x_i)} \cdots \int_{(x_i)}}^m$$

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Obviously, $\int^{(\alpha)}$ is a right inverse of ∂^α for $\alpha \in \mathbb{N}^n$. We remark that $\int^{(\alpha)} \partial^\alpha \neq 1$ if $\alpha \neq 0$ due to $\partial^\alpha(1) = 0$.

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Consider the wave equation in Riemannian space with a nontrivial conformal group:

$$u_{tt} - u_{x_1 x_1} - \sum_{i,j=2}^n g_{i,j}(x_1 - t) u_{x_i x_j} = 0, \quad (*)$$

where we assume that $g_{i,j}(z)$ are one-variable polynomials. Change variables:

$$z_0 = x_1 + t, \quad z_1 = x_1 - t.$$

Then

$$\partial_t^2 = (\partial_{z_0} - \partial_{z_1})^2, \quad \partial_{x_1}^2 = (\partial_{z_0} + \partial_{z_1})^2.$$

So the equation $(*)$ changes to:

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$$T_1 = 2\partial_{z_0}\partial_{z_1}, \quad T_2 = \sum_{i,j=2}^n g_{i,j}(z_1)\partial_{x_i}\partial_{x_j}.$$

Take $T_1^- = \frac{1}{2} \int_{(z_0)} \int_{(z_1)}$, and

$$\mathcal{B} = \mathbb{F}[z_0, z_1], \quad V = \mathbb{F}[x_2, \dots, x_n], \quad V_r = \{f \in V \mid \deg f \leq r\}.$$

Then the conditions in Lemma 1 hold. Thus we have:

Theorem 2. *The space of all polynomial solutions for the equation (*) is:*

$$\text{Span} \left\{ \sum_{m=0}^{\infty} (-2)^{-m} \left(\sum_{i,j=2}^n \int_{(z_0)} \int_{(z_1)} g_{i,j}(z_1) \partial_{x_i} \partial_{x_j} \right)^m (f_0 g_0 + f_1 g_1) \right. \\ \left. \mid f_0 \in \mathbb{F}[z_0], f_1 \in \mathbb{F}[z_1], g_0, g_1 \in \mathbb{F}[x_2, \dots, x_n] \right\}$$

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Let m_1, m_2, \dots, m_n be positive integers. According to Lemma 1, the set

$$\left\{ \sum_{k_2, \dots, k_n=0}^{\infty} (-1)^{k_2+\dots+k_n} \binom{k_2+\dots+k_n}{k_2, \dots, k_n} \int_{(x_1)}^{((k_2+\dots+k_n)m_1)} (x_1^{\ell_1}) \right. \\ \left. \times \partial_{x_2}^{k_2 m_2} (x_2^{\ell_2}) \dots \partial_{x_n}^{k_n m_n} (x_n^{\ell_n}) \mid \ell_1 \in \overline{0, m_1 - 1}, \ell_2, \dots, \ell_n \in \mathbb{N} \right\}$$

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Lemma 1 indeed gives an algorithm of finding polynomial solutions for more general equations.

Let

$$f_i \in \mathbb{R}[x_1, \dots, x_i] \quad \text{for } i \in \overline{1, n-1}.$$

Consider the equation:

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$$d_1 = \partial_{x_1}^{m_1}, \quad d_r = \partial_{x_1}^{m_1} + f_1 \partial_{x_2}^{m_2} + \cdots + f_{r-1} \partial_{x_r}^{m_r} \quad \text{for } r \in \overline{2, n}.$$

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We will apply Lemma 1 with $T_1 = d_r$, $T_2 = \sum_{i=r}^{n-1} f_i \partial_{x_{i+1}}^{m_{i+1}}$ inductively. Take a right inverse $d_1^- = \int_{(x_1)}^{(m_1)}$. Suppose that we have found a right inverse d_s^- of d_s for some $s \in \overline{1, n-1}$ such that

$$x_i d_s^- = d_s^- x_i, \quad \partial_{x_i} d_s^- = d_s^- \partial_{x_i} \quad \text{for } i \in \overline{s+1, n} \quad (**)$$

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$$d_{s+1}^- = \sum_{i=0}^{\infty} (-d_s^- f_s)^i d_s^- \partial_{x_{s+1}}^{im_{s+1}}$$

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We set

$$\mathcal{S}_r = \{g \in \mathbb{R}[x_1, \dots, x_r] \mid d_r(g) = 0\} \quad \text{for } r \in \overline{1, k}.$$

Then

$$\mathcal{S}_1 = \sum_{i=0}^{m_1-1} \mathbb{R}x_1^i.$$

Suppose that we have found \mathcal{S}_r for some $r \in \overline{1, n-1}$.

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Given $h \in \mathcal{S}_r$ and $\ell \in \mathbb{N}$, we define

$$\sigma_{r+1,\ell}(h) = \sum_{i=0}^{\infty} (-d_r^- f_r)^i(h) \partial_{x_{r+1}}^{im_{r+1}}(x_{r+1}^\ell),$$

which is actually a finite summation. Lemma 1 says

$$\mathcal{S}_{r+1} = \sum_{\ell=0}^{\infty} \sigma_{r+1,\ell}(\mathcal{S}_r).$$

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$$\{\sigma_{n,\ell_n}\sigma_{n-1,\ell_{n-1}}\cdots\sigma_{2,\ell_2}(x_1^{\ell_1}) \mid \ell_1 \in \overline{0, m_1 - 1}, \ell_2, \dots, \ell_n \in \mathbb{N}\}$$

forms a basis of the polynomial solution space \mathcal{S}_n of the partial differential equation:

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Evolution Equations

First we want to solve the following evolution partial differential equation:

$$u_t = (\partial_{x_1} + x_1^{m_1} \partial_{x_2} + x_2^{m_2} \partial_{x_3} + \cdots + x_{n-1}^{m_{n-1}} \partial_{x_n})(u)$$

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Theoretically, the solution is

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Practically, we often need an exact closed formula of the solution!

For convenience, we denote $m_0 = 1$ and $x_0 = 1$. Set

$$D_i = t \sum_{r=0}^{i-1} x_i^{m_i} \partial_{x_{i+1}} \quad \text{for } i \in \overline{1, n}.$$

Denote

$$A = D_n, \quad B = -tx_{n-1}^{m_{n-1}} \partial_{x_n}.$$

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In our special case, the Campbell-Hausdorff formula becomes

$$\ln e^A e^B = A + B + \sum_{r=1}^{\infty} a_r (\operatorname{ad} A)^r(B), \quad a_r \in \mathbb{R},$$

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After a long calculation, we obtain

$$e^{D_n} = e^{D_{n-1}} e^{t\vartheta(D_{n-1})(x_{n-1}^{m_{n-1}})\partial_{x_n}}.$$

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By induction, we get

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Moreover, we define

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$$\begin{aligned} \eta_i(t) = & \int_0^t (x_{i-1} + \int_0^{y_{i-1}} (x_{i-2} + \dots \\ & + \int_0^{y_2} (x_1 + y_1)^{m_1} dy_1 \dots)^{m_{i-2}} dy_{i-2})^{m_{i-1}} dy_{i-1}. \end{aligned}$$

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$$\eta_i(t) = \int_0^t (x_{i-1} + \int_0^{y_{i-1}} (x_{i-2} + \dots \\ + \int_0^{y_2} (x_1 + y_1)^{m_1} dy_1 \dots)^{m_{i-2}} dy_{i-2})^{m_{i-1}} dy_{i-1}.$$

Our final solution is

$$u = f(x_1 + \eta_1(t), x_2 + \eta_2(t), \dots, x_n + \eta_n(t)).$$

Indeed we have solve more general equations associated with weighted root trees in graph theory.

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Indeed we have solve more general equations associated with weighted root trees in graph theory.

Given a continuous function $f(x_1, x_2, \dots, x_n)$ on the region:

$$-a_i \leq x_i \leq a_i, \quad 0 < a_i \in \mathbb{R}, \quad \text{for } i \in \overline{1, n}.$$

We want to solve the differential equation:

$$u_t = (\partial_{x_1}^{m_1} + x_1 \partial_{x_2}^{m_2} + x_2 \partial_{x_3}^{m_3} + \cdots + x_{n-1} \partial_{x_n}^{m_n})(u)$$

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Denote

$$D(t) = t(\partial_{x_1}^{m_1} + x_1 \partial_{x_2}^{m_2} + x_2 \partial_{x_3}^{m_3} + \cdots + x_{n-1} \partial_{x_n}^{m_n}).$$

Define

$$\xi_1(t, \partial_{x_1}, \dots, \partial_{x_n}) = \int_0^t (\partial_{x_1} + \int_0^{y_1} (\partial_{x_2} + \dots + \int_0^{y_{n-2}} (\partial_{x_{n-1}} + y_{n-1} \partial_{x_n}^{m_n})^{m_{n-1}} dy_{n-1} \dots)^{m_2} dy_2)^{m_1} dy_1,$$

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Dual arguments show

$$e^D(t) = e^{\xi_n(t, \partial_{x_1}, \dots, \partial_{x_n})} e^{\xi_{n-1}(t, \partial_{x_1}, \dots, \partial_{x_n})} \dots e^{\xi_1(t, \partial_{x_1}, \dots, \partial_{x_n})}.$$

For convenience, we denote

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Set

$$e^{2\pi(\vec{k}^\dagger \cdot \vec{x})\sqrt{-1}} = e^{\sum_{r=1}^n 2\pi k_r^\dagger x_r \sqrt{-1}}.$$

Define

$$\begin{aligned} \phi_{\vec{k}}(t, x_1, \dots, x_n) = & \frac{1}{2} \left[\left(\prod_{i=1}^n e^{\xi_i(t, 2\pi k_1^\dagger \sqrt{-1}, \dots, 2\pi k_n^\dagger \sqrt{-1})} \right) e^{2\pi(\vec{k}^\dagger \cdot \vec{x})\sqrt{-1}} \right. \\ & \left. + \left(\prod_{i=1}^n e^{\xi_i(t, -2\pi k_1^\dagger \sqrt{-1}, \dots, -2\pi k_n^\dagger \sqrt{-1})} \right) e^{-2\pi(\vec{k}^\dagger \cdot \vec{x})\sqrt{-1}} \right] \end{aligned}$$

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Then

$$\phi_{\vec{k}}(0, x_1, \dots, x_n) = \cos 2\pi(\vec{k}^\dagger \cdot \vec{x}),$$

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We define $0 \prec \vec{k}$ if its first nonzero coordinate is a positive integer.
The solution of our second problem is

$$u = \sum_{0 \prec \vec{k} \in \mathbb{Z}^n} (b_{\vec{k}} \phi_{\vec{k}}(t, x_1, \dots, x_n) + c_{\vec{k}} \psi_{\vec{k}}(t, x_1, \dots, x_n))$$

with

$$b_{\vec{k}} = \frac{1}{2^{n-1} a_1 a_2 \cdots a_n} \int_{-a_1}^{a_1} \cdots \int_{-a_n}^{a_n} f(x_1, \dots, x_n) \cos 2\pi(\vec{k}^\dagger \cdot \vec{x}) dx_n \cdots dx_1$$

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Constant-Coefficient PDEs

Let m and $n > 1$ be positive integers and let

$$f_i(\partial_{x_2}, \dots, \partial_{x_n}) \in \mathbb{R}[\partial_{x_2}, \dots, \partial_{x_n}] \quad \text{for } i \in \overline{1, m}.$$

We want to solve the equation:

$$(\partial_{x_1}^m - \sum_{r=1}^m \partial_{x_1}^{m-r} f_r(\partial_{x_2}, \dots, \partial_{x_n}))(u) = 0$$

with $x_1 \in \mathbb{R}$ and $x_r \in [-a_r, a_r]$ for $r \in \overline{2, n}$, subject to the condition

$$\partial_{x_1}^s(u)(0, x_2, \dots, x_n) = g_s(x_2, \dots, x_n) \quad \text{for } s \in \overline{0, m-1},$$

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For $r \in \overline{0, m-1}$, as Lemma 1,

$$\begin{aligned}
 & \frac{1}{r!} \sum_{i_1, \dots, i_m=0}^{\infty} \binom{i_1 + \dots + i_m}{i_1, \dots, i_m} \int_{(x_1)}^{(\sum_{s=1}^m s i_s)} (x_1^r) \\
 & \times \left(\prod_{p=1}^m f_p(\partial_{x_2}, \dots, \partial_{x_n})^{i_p} \right) (e^{2\pi(\vec{k}^\dagger \cdot \vec{x})\sqrt{-1}}) \\
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is a complex solution of the equation for any $\vec{k} \in \mathbb{Z}^{n-1}$.

For $r \in \overline{0, m-1}$, as Lemma 1,

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We write

$$\begin{aligned} & \sum_{i_1, \dots, i_m=0}^{\infty} \binom{i_1 + \dots + i_m}{i_1, \dots, i_m} \\ & \times \frac{x_1^r \prod_{p=1}^m (x_1^p f_p(2k_2^\dagger \pi \sqrt{-1}, \dots, 2k_n^\dagger \pi \sqrt{-1}))^{i_p}}{(r + \sum_{s=1}^m s i_s)!} \\ & = \phi_r(x_1, \vec{k}) + \psi_r(x_1, \vec{k}) \sqrt{-1}, \end{aligned}$$

where $\phi_r(x_1, \vec{k})$ and $\psi_r(x_1, \vec{k})$ are real functions. Moreover,

$$\partial_{x_1}^s (\phi_r)(0, \vec{k}) = \delta_{r,s}, \quad \partial_{x_1}^s (\psi_r)(0, \vec{k}) = 0 \quad \text{for } s \in \overline{0, r}.$$

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The solution of our initial-value problem is:

$$\begin{aligned}
 u = & \sum_{r=0}^{m-1} \sum_{\vec{0} \preceq \vec{k} \in \mathbb{Z}^{n-1}} [b_r(\vec{k})(\phi_r(x_1, \vec{k}^\dagger) \cos 2\pi(\vec{k}^\dagger \cdot \vec{x}) \\
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 b_r(\vec{k}) &= \frac{1}{2^{n-2} a_2 \cdots a_n} \int_{-a_2}^{a_2} \cdots \int_{-a_n}^{a_n} g_r(x_2, \dots, x_n) \\
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Remark . If we take $f_i = b_i$ with $i \in \overline{1, m}$ to be constant functions, we get m fundamental solutions

$$\varphi_r(x) = \sum_{i_1, \dots, i_m=0}^{\infty} \binom{i_1 + \dots + i_m}{i_1, \dots, i_m} \frac{x^r \prod_{p=1}^m (b_p x^p)^{i_p}}{(r + \sum_{s=1}^m s i_s)!}, \quad r \in \overline{0, m-1}$$

of the constant-coefficient ordinary differential equation

$$y^{(m)} - b_1 y^{(m-1)} - \dots - b_{m-1} y' - b_m = 0.$$

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From the above results, it seems that the following functions

$$\mathcal{Y}_r(y_1, \dots, y_m) = \sum_{i_1, \dots, i_m=0}^{\infty} \binom{i_1 + \dots + i_m}{i_1, \dots, i_m} \frac{y_1^{i_1} y_2^{i_2} \dots y_m^{i_m}}{(r + \sum_{s=1}^m s i_s)!} \quad \text{for } r \in \mathbb{N}$$

are important natural functions. Indeed,

$$\mathcal{Y}_1(x) = e^x, \quad \mathcal{Y}_0(0, -x) = \cos x, \quad \mathcal{Y}_1(0, -x) = \frac{\sin x}{x},$$

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Reference:

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Thank You!