

Classical Yang-Baxter Equation and Its Extensions

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- 1 What is classical Yang-Baxter equation (CYBE)?
- 2 Extensions of CYBE: Lie algebras
- 3 Extensions of CYBE: general algebras

What is classical Yang-Baxter equation (CYBE)?

Definition

Let $\mathfrak{g}$ be a Lie algebra and $r = \sum_i a_i \otimes b_i \in \mathfrak{g} \otimes \mathfrak{g}$. r is called a solution of **classical Yang-Baxter equation (CYBE)** in $\mathfrak{g}$ if

$$[r_{12}, r_{13}] + [r_{12}, r_{23}] + [r_{13}, r_{23}] = 0 \text{ in } U(\mathfrak{g}), \quad (1)$$

where $U(\mathfrak{g})$ is the universal enveloping algebra of $\mathfrak{g}$ and

$$r_{12} = \sum_i a_i \otimes b_i \otimes 1; r_{13} = \sum_i a_i \otimes 1 \otimes b_i; r_{23} = \sum_i 1 \otimes a_i \otimes b_i. \quad (2)$$

r is said to be **skew-symmetric** if

$$r = \sum_i (a_i \otimes b_i - b_i \otimes a_i). \quad (3)$$

We also denote $r^{21} = \sum_i b_i \otimes a_i$.

What is classical Yang-Baxter equation (CYBE)?

- Background and application:

- 1 Arose in the study of inverse scattering theory.
- 2 Schouten bracket in differential geometry.
- 3 “Classical limit” of quantum Yang-Baxter equation.
- 4 Classical integrable systems (Lax pair approach).
- 5 Lie bialgebras (coboundary Lie bialgebras).
- 6 Symplectic geometry (invertible solutions).
- 7 ...

What is classical Yang-Baxter equation (CYBE)?

- Interpretation in terms of matrices (linear maps)

★ Classical r -matrix

Set $r = \sum_{i,j} r_{ij} e_i \otimes e_j$, where $\{e_1, \dots, e_j\}$ is a basis of the Lie algebra $\mathfrak{g}$. Then the matrix

$$r = (r_{ij}) = \begin{pmatrix} r_{11} & \cdots & r_{1n} \\ \cdots & \cdots & \cdots \\ r_{n1} & \cdots & r_{nn} \end{pmatrix}, \quad (6)$$

is called a **classical r -matrix**.

Natural question: if a linear transformation (or generally, a linear map) R is given by the classical r -matrix under a basis, what should r satisfy?

What is classical Yang-Baxter equation (CYBE)?

★ Semenov-Tian-Shansky's approach: Operator form of CYBE (Rota-Baxter operator)

*M.A. Semenov-Tian-Shansky, What is a classical R-matrix? Funct. Anal. Appl. **17** (1983) 259-272.*

A linear map $R : \mathfrak{g} \rightarrow \mathfrak{g}$ satisfies

$$[R(x), R(y)] = R([R(x), y] + [x, R(y)]), \forall x, y \in \mathfrak{g}. \quad (7)$$

It is equivalent to the tensor form (1) of CYBE under the following two conditions:

- 1 there exists a nondegenerate symmetric invariant bilinear form on $\mathfrak{g}$.
- 2 r is skew-symmetric.

What is classical Yang-Baxter equation (CYBE)?

On the other hand, it is exactly the **Rota-Baxter operator (of weight zero)** in the context of Lie algebras:

$$R(x)R(y) = R(R(x)y + xR(y)), \forall x \in A, \quad (8)$$

where A is an associative algebra and $R : A \rightarrow A$ is a linear map.

Rota-Baxter operators arose from probability and combinatorics and have connections with many fields.

(See *L. Guo, WHAT is a Rota-Baxter algebra, Notice of Amer. Math. Soc.* **56** (2009) 1436-1437)

What is classical Yang-Baxter equation (CYBE)?

★ Kupershmidt's approach: $\mathcal{O}$ -operators

B.A. Kupershmidt, What a classical r -matrix really is, J. Nonlinear Math. Phys. **6** (1999), 448-488.

When r is skew-symmetric, the tensor form (1) of CYBE is equivalent to a linear map $r : \mathfrak{g}^* \rightarrow \mathfrak{g}$ satisfying

$$[r(x), r(y)] = r(\text{ad}^* r(x)(y) - \text{ad}^* r(y)(x)), \forall x, y \in \mathfrak{g}^*, \quad (9)$$

where $\mathfrak{g}^*$ is the dual space of $\mathfrak{g}$ and ad^* is the dual representation of adjoint representation (coadjoint representation).

Definition

Let $\mathfrak{g}$ be a Lie algebra and $\rho : \mathfrak{g} \rightarrow \mathfrak{gl}(V)$ be a representation of $\mathfrak{g}$. A linear map $T : V \rightarrow \mathfrak{g}$ is called an **$\mathcal{O}$ -operator** if T satisfies

$$[T(u), T(v)] = T(\rho(T(u))v - \rho(T(v))u), \forall u, v \in V. \quad (10)$$

Kupershmidt introduced the notion of $\mathcal{O}$ -operator as a natural generalization of CYBE!

What is classical Yang-Baxter equation (CYBE)?

★ “Duality” between Rota-Baxter operators and CYBE

R is a Rota-Baxter operator of weight zero
 $\iff$ an $\mathcal{O}$ -operator associated to ad

When r is skew-symmetric, we know that
CYBE $\iff$ an $\mathcal{O}$ -operator associated to ad^*
(From CYBE to $\mathcal{O}$ -operators)

What is classical Yang-Baxter equation (CYBE)?

- From $\mathcal{O}$ -operators to CYBE

C. Bai, A unified algebraic approach to the classical Yang-Baxter equation, J. Phys. A **40** (2007) 11073-11082.

Notation: let $\rho : \mathfrak{g} \rightarrow gl(V)$ be a representation of the Lie algebra $\mathfrak{g}$. On the vector space $\mathfrak{g} \oplus V$, there is a natural Lie algebra structure (denoted by $\mathfrak{g} \ltimes_{\rho} V$) given as follows:

$$[x_1 + v_1, x_2 + v_2] = [x_1, x_2] + \rho(x_1)v_2 - \rho(x_2)v_1, \quad (11)$$

for any $x_1, x_2 \in \mathfrak{g}, v_1, v_2 \in V$.

Proposition

Let $\mathfrak{g}$ be a Lie algebra. Let $\rho : \mathfrak{g} \rightarrow gl(V)$ be a representation of $\mathfrak{g}$ and $\rho^* : \mathfrak{g} \rightarrow gl(V^*)$ be the dual representation. Let $T : V \rightarrow \mathfrak{g}$ be a linear map which is identified as an element in $\mathfrak{g} \otimes V^* \subset (\mathfrak{g} \ltimes_{\rho^*} V^*) \otimes (\mathfrak{g} \ltimes_{\rho} V)$. Then $r = T - T^{21}$ is a skew-symmetric solution of CYBE in $\mathfrak{g} \ltimes_{\rho^*} V^*$ if and only if T is an $\mathcal{O}$ -operator.

What is classical Yang-Baxter equation (CYBE)?

- Left-symmetric algebras: the algebra structures behind CYBE ($\mathcal{O}$ -operators approach)

Definition

Let A be a vector space equipped with a bilinear product $(x, y) \rightarrow xy$. A is called a **left-symmetric algebra** if

$$(xy)z - x(yz) = (yx)z - y(xz), \forall x, y, z \in A. \quad (12)$$

Two basic properties:

- 1 The commutator

$$[x, y] = xy - yx, \quad \forall x, y \in A, \quad (13)$$

defines a Lie algebra $\mathfrak{g}(A)$, which is called the sub-adjacent Lie algebra of A and A is also called the compatible left-symmetric algebra structure on the Lie algebra $\mathfrak{g}(A)$.

- 2 $L : \mathfrak{g}(A) \rightarrow gl(\mathfrak{g}(A))$ with $x \rightarrow L_x$ gives a regular representation of the Lie algebra $\mathfrak{g}(A)$.

What is classical Yang-Baxter equation (CYBE)?

★ From $\mathcal{O}$ -operators to left-symmetric algebras

Let $\mathfrak{g}$ be a Lie algebra and $\rho : \mathfrak{g} \rightarrow \mathfrak{gl}(V)$ be a representation. Let $T : V \rightarrow \mathfrak{g}$ be an $\mathcal{O}$ -operator associated to ρ , then

$$u * v = \rho(T(u))v, \quad \forall u, v \in V \quad (14)$$

defines a left-symmetric algebra on V .

★ Sufficient and necessary condition:

Proposition

Let $\mathfrak{g}$ be a Lie algebra. There is a compatible left-symmetric algebra structure on $\mathfrak{g}$ if and only if there exists an invertible $\mathcal{O}$ -operator of $\mathfrak{g}$.

“ $\Leftarrow$ ” The left-symmetric algebra structure is given by

$$x \circ y = T(\rho(x)T^{-1}(y)), \quad \forall x, y \in \mathfrak{g}. \quad (15)$$

“ $\Rightarrow$ ” $\text{id} : \mathfrak{g}(A) \rightarrow \mathfrak{g}(A)$ is an $\mathcal{O}$ -operator of $\mathfrak{g}(A)$ associated to the representation $(L_\circ, A)$.

What is classical Yang-Baxter equation (CYBE)?

★ From left-symmetric algebras to CYBE

Proposition

Let A be a left-symmetric algebra. Then

$$r = \sum_{i=1}^n (e_i \otimes e_i^* - e_i^* \otimes e_i) \quad (16)$$

is a solution of the classical Yang-Baxter equation in the Lie algebra $\mathfrak{g}(A) \ltimes_{L^} \mathfrak{g}(A)^*$, where $\{e_1, \dots, e_n\}$ is a basis of A and $\{e_1^*, \dots, e_n^*\}$ is the dual basis.*

- Motivations and some examples

★ Semenov-Tian-Shansky's **modified classical Yang-Baxter equation (MCYBE)**

Let $\mathfrak{g}$ be a Lie algebra. A linear map $R : \mathfrak{g} \rightarrow \mathfrak{g}$ is a solution of the MCYBE if R satisfies

$$[R(x), R(y)] - R([R(x), y] + [x, R(y)]) = -[x, y], \forall x, y \in \mathfrak{g}. \quad (17)$$

Extensions of CYBE: Lie algebras

★ Bordemann's generalization of MCYBE

M. Bordemann, Generalized Lax pairs, the modified classical Yang-Baxter equation, and affine geometry of Lie groups, Comm. Math. Phys. **135** (1990) 201-216.

Let $\rho : \mathfrak{g} \rightarrow gl(V)$ be a representation of a Lie algebra $\mathfrak{g}$. Set

$$x \cdot v =: \rho(x)v, \quad \forall x \in \mathfrak{g}, v \in V. \quad (18)$$

Let $\beta : V \rightarrow \mathfrak{g}$ be a linear map satisfies

$$\beta(u) \cdot v + \beta(v) \cdot u = 0, \quad \forall u, v \in V; \quad (19)$$

$$\beta(x \cdot v) = [x, \beta(v)], \quad \forall x \in \mathfrak{g}, v \in V. \quad (20)$$

A linear map $r : V \rightarrow \mathfrak{g}$ satisfies MCYBE if r satisfies

$$[r(u), r(v)] = r(r(u) \cdot v - r(v) \cdot u) - [\beta(u), \beta(v)], \quad \forall u, v \in V. \quad (21)$$

- 1 When $\beta = 0$, r is the $\mathcal{O}$ -operator;
- 2 When $\rho = \text{ad}$ and $\beta = \text{id}$, r reduces to the S.-T.-S.'s MCYBE.

★ Rota-Baxter operator of any weight

Let $\mathfrak{g}$ be a Lie algebra. A linear map $R : \mathfrak{g} \rightarrow \mathfrak{g}$ is called a Rota-Baxter operator of weight λ if R satisfies

$$[R(x), R(y)] = R([R(x), y] + [x, R(y)] + \lambda[x, y]), \forall x, y \in \mathfrak{g}. \quad (22)$$

★ Questions:

- 1 Whether it is possible to extend the notion of $\mathcal{O}$ -operator to the non-zero weight?
- 2 If (1) holds, whether it is possible to deal with it and the Bordemann's generalization by a unified way?
- 3 Whether there are the tensor forms related to the above operator forms?
- 4 How to deal with the non-skew-symmetric cases?

Extensions of CYBE: Lie algebras

- Extended $\mathcal{O}$ -operators and extended CYBE
- ★ Extensions from representations to $\mathfrak{g}$ -Lie algebras

Definition

- 1 Let $(\mathfrak{g}, [\cdot, \cdot]_{\mathfrak{g}})$, or simply $\mathfrak{g}$, denote a Lie algebra $\mathfrak{g}$ with Lie bracket $[\cdot, \cdot]_{\mathfrak{g}}$.
- 2 For a Lie algebra $\mathfrak{b}$, let $\text{Der}_{\mathbf{k}}\mathfrak{b}$ denote the Lie algebra of derivations of $\mathfrak{b}$.
- 3 Let $\mathfrak{a}$ be a Lie algebra. An **$\mathfrak{a}$ -Lie algebra** is a triple $(\mathfrak{b}, [\cdot, \cdot]_{\mathfrak{b}}, \pi)$ consisting of a Lie algebra $(\mathfrak{b}, [\cdot, \cdot]_{\mathfrak{b}})$ and a Lie algebra homomorphism $\pi : \mathfrak{a} \rightarrow \text{Der}_{\mathbf{k}}\mathfrak{b}$. To simplify the notation, we also let $(\mathfrak{b}, \pi)$ or simply $\mathfrak{b}$ denote $(\mathfrak{b}, [\cdot, \cdot]_{\mathfrak{b}}, \pi)$.
- 4 Let $\mathfrak{a}$ be a Lie algebra and let $(\mathfrak{g}, \pi)$ be an $\mathfrak{a}$ -Lie algebra. Let $a \cdot b$ denote $\pi(a)b$ for $a \in \mathfrak{a}$ and $b \in \mathfrak{g}$.

Proposition

Let $\mathfrak{a}$ be a Lie algebra and let $(\mathfrak{b}, \pi)$ be an $\mathfrak{a}$ -Lie algebra. Then there exists a unique Lie algebra structure on the vector space direct sum $\mathfrak{g} = \mathfrak{a} \oplus \mathfrak{b}$ retaining the old brackets in $\mathfrak{a}$ and $\mathfrak{b}$ and satisfying $[x, a] = \pi(x)a$ for $x \in \mathfrak{a}$ and $a \in \mathfrak{b}$. That is,

$$[x+a, y+b] = [x, y] + \pi(x)b - \pi(y)a + [a, b], \forall x, y \in \mathfrak{a}, a, b \in \mathfrak{b}. \quad (23)$$

Extensions of CYBE: Lie algebras

★ Extensions of $\mathcal{O}$ -operators

Definition

Let $\mathfrak{g}$ be a Lie algebra and $\mathfrak{k}$ be a $\mathfrak{g}$ -Lie algebra. Let $\alpha, \beta : \mathfrak{k} \rightarrow \mathfrak{g}$ be two linear maps. Suppose that

$$\kappa\beta(x) \cdot y + \kappa\beta(y) \cdot x = 0, \forall x, y \in \mathfrak{k} \quad (24)$$

$$\kappa\beta(\xi \cdot x) = \kappa[\xi, \beta(x)], \forall \xi \in \mathfrak{g}, x \in \mathfrak{k}, \quad (25)$$

$$\mu\beta([x, y]) \cdot z = \mu[\beta(x) \cdot y, z], \forall x, y, z \in \mathfrak{k}, \quad (26)$$

The pair (α, β) or simply α is called an **extended $\mathcal{O}$ -operator of weight λ with extension β of mass (κ, μ)** if

$$\begin{aligned} & [\alpha(x), \alpha(y)]_{\mathfrak{g}} - \alpha(\alpha(x) \cdot y - \alpha(y) \cdot x + \lambda[x, y]_{\mathfrak{k}}) \\ &= \kappa[\beta(x), \beta(y)]_{\mathfrak{g}} + \mu\beta([x, y]_{\mathfrak{k}}), \forall x, y \in \mathfrak{k}. \end{aligned} \quad (27)$$

Definition

When (V, ρ) is a $\mathfrak{g}$ -module, we regard (V, ρ) as a $\mathfrak{g}$ -Lie algebra with the trivial bracket. Then λ, μ are irrelevant. We then call the pair (α, β) **an extended $\mathcal{O}$ -operator with extension β of mass κ** .

- 1 If (V, ρ) is a $\mathfrak{g}$ -module (or $\lambda = \mu = 0$), and in addition $\kappa = -1$, we obtain the Bordemann's MCYBE;
- 2 When $\beta = 0$, we obtain an **$\mathcal{O}$ -operator of weight $\lambda \in \mathbf{k}$** , i.e.,

$$[\alpha(x), \alpha(y)]_{\mathfrak{g}} = \alpha(\alpha(x) \cdot y - \alpha(y) \cdot x + \lambda[x, y]_{\mathfrak{k}}), \quad \forall x, y \in \mathfrak{k}. \quad (28)$$

If in addition, $(\mathfrak{k}, \pi) = (\mathfrak{g}, \text{ad})$, we obtain the Rota-Baxter operator of weight λ .

★ Extensions of CYBE

Definition

Let $\mathfrak{g}$ be a Lie algebra. Fix $\epsilon \in \mathbb{R}$. The equation

$$[r_{12}, r_{13}] + [r_{12}, r_{23}] + [r_{13}, r_{23}] = \epsilon[(r_{13} + r_{31}), (r_{23} + r_{32})] \quad (29)$$

is called the **extended classical Yang-Baxter equation (ECYBE) of mass ϵ** .

When $\epsilon = 0$ or r is skew-symmetric, then the ECYBE of mass ϵ is the same as the CYBE.

★ From extended CYBE to extended $\mathcal{O}$ -operators

*C. Bai, L. Guo and X. Ni, Nonabelian generalized Lax pairs, the classical Yang-Baxter equation and PostLie algebras, Comm. Math. Phys. **297** (2010) 553-596.*

C. Bai, L. Guo and X. Ni, Generalizations of the classical Yang-Baxter equation and $\mathcal{O}$ -operators, preprint 2010.

Notations: Let $\mathfrak{g}$ be a Lie algebra and let $r \in \mathfrak{g} \otimes \mathfrak{g}$. Set

$$r_{\pm} = (r \pm r^{21})/2. \quad (30)$$

On the other hand, $r \in \mathfrak{g} \otimes \mathfrak{g}$ is said to be **invariant** if r satisfies

$$(\mathrm{ad}(x) \otimes \mathrm{id} + \mathrm{id} \otimes \mathrm{ad}(x))r = 0, \forall x \in \mathfrak{g}. \quad (31)$$

Theorem

Let $\mathfrak{g}$ be a Lie algebra and let $r \in \mathfrak{g} \otimes \mathfrak{g}$. Define $r_{\pm}$ by Eq. (30) which are identified as linear maps from $\mathfrak{g}^*$ to $\mathfrak{g}$. Suppose that r_+ is invariant. Then r is a solution of ECYBE of mass $\frac{\kappa+1}{4}$:

$$[r_{12}, r_{13}] + [r_{12}, r_{23}] + [r_{13}, r_{23}] = \frac{\kappa + 1}{4} [(r_{13} + r_{31}), (r_{23} + r_{32})] \quad (32)$$

if and only if r_- is an extended $\mathcal{O}$ -operator with extension r_+ of mass κ , i.e., the following equation holds:

$$\begin{aligned} [r_-(a^*), r_-(b^*)] - r_-(\text{ad}^*(r_-(a^*))b^* - \text{ad}^*(r_-(b^*))a^*) \\ = \kappa[r_+(a^*), r_+(b^*)], \quad \forall a^*, b^* \in \mathfrak{g}^*. \end{aligned} \quad (33)$$

Special cases:

(1) *Y. Kosmann-Schwarzbach and F. Magri, Poisson-Lie groups and complete integrability, I. Drinfeld bialgebras, dual extensions and their canonical representations, Ann. Inst. Henri Poincaré, Phys. Théor. A* **49** (1988) 433-460.

Suppose that r is not skew-symmetric. If the symmetric part r_+ is invariant, then r is a solution of the CYBE if and only if r_- is an extended $\mathcal{O}$ -operator with extension r_+ of mass -1 .

(2) Let $\mathfrak{g}$ be a real Lie algebra and $r \in \mathfrak{g} \otimes \mathfrak{g}$. Then

$$[r_{12}, r_{13}] + [r_{12}, r_{23}] + [r_{13}, r_{23}] = \frac{1}{2}[r_{13} + r_{31}, r_{23} + r_{32}] \quad (32)$$

is called the **type II CYBE**.

Suppose r_+ is invariant.

r is a solution of the type II CYBE.

$\Leftrightarrow r_-$ is an extended $\mathcal{O}$ -operator with extension r_+ of mass 1.

$\Leftrightarrow r_- \pm ir_+$ are solutions of the CYBE in $\mathfrak{g} \oplus \sqrt{-1}\mathfrak{g}$.

Extensions of CYBE: Lie algebras

★ From extended $\mathcal{O}$ -operators to extended CYBE

Let $\mathfrak{g}$ be a Lie algebra and let (V, ρ) be a $\mathfrak{g}$ -module.

- ❶ Let $\alpha, \beta : V \rightarrow \mathfrak{g}$ be linear maps. Then α is an extended $\mathcal{O}$ -operator with extension β of mass k if and only if $(\alpha - \alpha^{21} \pm (\beta + \beta^{21}))$ is a solution of ECYBE of mass $\frac{\kappa+1}{4}$ in $\mathfrak{g} \ltimes_{\rho^*} V^*$.
- ❷ Let $\alpha : V \rightarrow \mathfrak{g}$ be a linear map. Then α is an $\mathcal{O}$ -operator of weight zero if and only if $\alpha - \alpha^{21}$ is a skew-symmetric solution of CYBE in $\mathfrak{g} \ltimes_{\rho^*} V^*$.
- ❸ Let $R : \mathfrak{g} \rightarrow \mathfrak{g}$ be a linear map. R satisfies Semenov-Tian-Shansky's MCYBE if and only if $R - R^{21} \pm (\text{id} + \text{id}^{21})$ is a solution of CYBE in $\mathfrak{g} \ltimes_{\text{ad}^*} \mathfrak{g}^*$.
- ❹ Let $P : \mathfrak{g} \rightarrow \mathfrak{g}$ be a linear map. Then P is a Rota-Baxter operator of weight $\lambda \neq 0$ if and only if both $\frac{2}{\lambda}(P - P^{21}) + 2\text{id}$ and $\frac{2}{\lambda}(P - P^{21}) - 2\text{id}^{21}$ are solutions of CYBE in $\mathfrak{g} \ltimes_{\text{ad}^*} \mathfrak{g}^*$.

★ Applications in integrable systems

Definition

A **nonabelian generalized Lax pair** for a Hamiltonian system $(P, w, \mathcal{H})$ is a quintuple $(\mathfrak{g}, \rho, \mathfrak{a}, L, M)$ satisfying the following conditions:

- ① $\mathfrak{g}$ is a (finite-dimensional) Lie algebra;
- ② $(\mathfrak{a}, \rho)$ is a (finite-dimensional) $\mathfrak{g}$ -Lie algebra with the Lie algebra homomorphism $\rho : \mathfrak{g} \rightarrow \text{Der}_{\mathbb{R}}(\mathfrak{a})$;
- ③ $L : P \rightarrow \mathfrak{a}$ is a smooth map,
- ④ $M : P \rightarrow \mathfrak{g}$ is a smooth map such that

$$dL(p)X_{\mathcal{H}}(p) = -\rho(M(p))L(p), \quad \forall p \in P. \quad (35)$$

Extensions of CYBE: Lie algebras

- 1 When the Lie bracket on $\mathfrak{a}$ happens to be trivial, the $\mathfrak{g}$ -Lie algebra $(\mathfrak{a}, \rho)$ becomes a representation of $\mathfrak{g}$ and the nonabelian generalized Lax pair becomes the **generalized Lax pair** in the sense of Bordemann.
- 2 For $\mathfrak{a} = \mathfrak{g}$ and $\rho = \text{ad}$, Eq. (35) is the usual **Lax equation**. Moreover, the Lax pair can be realized as a nonabelian generalized Lax pair in two different ways, by either taking ρ to be ad and $\mathfrak{a}$ to be the Lie algebra $\mathfrak{g}$, or taking ρ to be ad and $\mathfrak{a}$ to be the underlying vector space of $\mathfrak{g}$ equipped with the trivial Lie bracket.

Remark

Nonabelian generalized r -matrix ansatz gives a natural motivation to extended $\mathcal{O}$ -operators.

Extensions of CYBE: Lie algebras

★ New algebras behind: PostLie algebras

B. Vallette, Homology of generalized partition posets, J. Pure Appl. Algebra **208** (2007) 699-725.

Definition

A **(left) PostLie algebra** is a $\mathbb{R}$ -vector space L with two bilinear operations $\circ$ and $[\cdot, \cdot]$ which satisfy the relations:

$$[x, y] = -[y, x], \quad (36)$$

$$[[x, y], z] + [[z, x], y] + [[y, z], x] = 0, \quad (37)$$

$$z \circ (y \circ x) - y \circ (z \circ x) + (y \circ z) \circ x - (z \circ y) \circ x + [y, z] \circ x = 0, \quad (38)$$

$$z \circ [x, y] - [z \circ x, y] - [x, z \circ y] = 0, \quad (39)$$

for all $x, y \in L$.

Extensions of CYBE: Lie algebras

Eq. (36) and Eq. (37) mean that L is a Lie algebra for the bracket $[\cdot, \cdot]$, and we denote it by $(\mathfrak{G}(L), [\cdot, \cdot])$. Moreover, we say that $(L, [\cdot, \cdot], \circ)$ **is a PostLie algebra structure on** $(\mathfrak{G}(L), [\cdot, \cdot])$. On the other hand, it is straightforward to check that L is also a Lie algebra for the operation:

$$\{x, y\} \equiv x \circ y - y \circ x + [x, y], \quad \forall x, y \in L. \quad (40)$$

We shall denote it by $(\mathcal{G}(L), \{\cdot, \cdot\})$ and say that $(\mathcal{G}(L), \{\cdot, \cdot\})$ **has a compatible PostLie algebra structure given by** $(L, [\cdot, \cdot], \circ)$.

Proposition

Let $\mathfrak{g}$ be a Lie algebra. Then there is a compatible PostLie algebra structure on $\mathfrak{g}$ if and only if there exists a $\mathfrak{g}$ -Lie algebra $(\mathfrak{k}, \pi)$ and an invertible $\mathcal{O}$ -operator $r : \mathfrak{k} \rightarrow \mathfrak{g}$ of weight 1.

Application: There is a typical example of nonabelian generalized Lax pair constructed from PostLie algebras!

Extensions of CYBE: Lie algebras

- Lie bialgebras and generalized CYBE

V. Chari and A. Pressley, A guide to quantum groups, Cambridge University Press, Cambridge (1994).

★ Lie bialgebras:

Definition

Let $\mathfrak{g}$ be a Lie algebra. A **Lie bialgebra** structure on $\mathfrak{g}$ is an antisymmetric linear map $\delta : \mathfrak{g} \rightarrow \mathfrak{g} \otimes \mathfrak{g}$ such that $\delta^* : \mathfrak{g}^* \otimes \mathfrak{g}^* \rightarrow \mathfrak{g}^*$ is a Lie bracket on $\mathfrak{g}^*$ and δ is a 1-cocycle of $\mathfrak{g}$ associated to $\text{ad} \otimes \text{id} + \text{id} \otimes \text{ad}$ with values in $\mathfrak{g} \otimes \mathfrak{g}$:

$$\begin{aligned} \delta([x, y]) &= (\text{ad}(x) \otimes \text{id} + \text{id} \otimes \text{ad}(x))\delta(y) - (\text{ad}(y) \otimes \text{id} \\ &\quad + \text{id} \otimes \text{ad}(y))\delta(x), \end{aligned} \tag{41}$$

for any $x, y \in \mathfrak{g}$. We denote it by $(\mathfrak{g}, \delta)$.

Extensions of CYBE: Lie algebras

★ Coboundary Lie bialgebras:

Definition

A Lie bialgebra $(\mathfrak{g}, \delta)$ is called **coboundary** if δ is a 1-coboundary of $\mathfrak{g}$ associated to $\text{ad} \otimes \text{id} + \text{id} \otimes \text{ad}$, that is, there exists an $r \in \mathfrak{g} \otimes \mathfrak{g}$ such that

$$\delta(x) = (\text{ad}(x) \otimes \text{id} + \text{id} \otimes \text{ad}(x))r, \quad \forall x \in \mathfrak{g}. \quad (42)$$

Theorem

Let $\mathfrak{g}$ be a Lie algebra and $r \in \mathfrak{g} \otimes \mathfrak{g}$. Then the map $\delta : \mathfrak{g} \rightarrow \mathfrak{g} \otimes \mathfrak{g}$ defined by Eq. (42) induces a Lie bialgebra structure on $\mathfrak{g}$ if and only if the following two conditions are satisfied (for any $x \in \mathfrak{g}$):

- ❶ $(\text{ad}(x) \otimes \text{id} + \text{id} \otimes \text{ad}(x))(r + r^{21}) = 0;$
- ❷ $(\text{ad}(x) \otimes \text{id} \otimes \text{id} + \text{id} \otimes \text{ad}(x) \otimes \text{id} + \text{id} \otimes \text{id} \otimes \text{ad}(x))([r_{12}, r_{13}] + [r_{12}, r_{23}] + [r_{13}, r_{23}]) = 0.$

★ Generalized CYBE:

Definition

Let $\mathfrak{g}$ be a Lie algebra and let $r \in \mathfrak{g} \otimes \mathfrak{g}$. r is said to be a solution of **generalized classical Yang-Baxter equation (GCYBE)** if r satisfies

$$\begin{aligned} &(\operatorname{ad}(x) \otimes \operatorname{id} \otimes \operatorname{id} + \operatorname{id} \otimes \operatorname{ad}(x) \otimes \operatorname{id} + \operatorname{id} \otimes \operatorname{id} \otimes \operatorname{ad}(x)) \\ &([r_{12}, r_{13}] + [r_{12}, r_{23}] + [r_{13}, r_{23}]) = 0. \end{aligned} \quad (43)$$

Extensions of CYBE: Lie algebras

Let $\mathfrak{g}$ be a Lie algebra.

- 1 If the symmetric part of $r \in \mathfrak{g} \otimes \mathfrak{g}$ is invariant, then r is a solution of GCYBE if r satisfies ECYBE.
- 2 Let $(\mathfrak{k}, \pi)$ be a $\mathfrak{g}$ -Lie algebra. Let $\alpha, \beta : \mathfrak{k} \rightarrow \mathfrak{g}$ be two linear maps such that α is an extended $\mathcal{O}$ -operator of weight λ with extension β of mass (κ, μ) . Then $\alpha - \alpha^{21} \in (\mathfrak{g} \ltimes_{\pi^*} \mathfrak{k}^*) \otimes (\mathfrak{g} \ltimes_{\pi^*} \mathfrak{k}^*)$ is a skew-symmetric solution of GCYBE if and only if the following equations hold:

$$\lambda\pi(\alpha([u, v]_{\mathfrak{k}}))w + \lambda\pi(\alpha([w, u]_{\mathfrak{k}}))v + \lambda\pi(\alpha([v, w]_{\mathfrak{k}}))u = 0, \quad (44)$$

$$\lambda[x, \alpha([u, v]_{\mathfrak{k}})]_{\mathfrak{g}} = \lambda\alpha([\pi(x)u, v]_{\mathfrak{k}}) + \lambda\alpha([u, \pi(x)v]_{\mathfrak{k}}), \quad (45)$$

for any $x \in \mathfrak{g}, u, v, w \in \mathfrak{k}$. In particular, if $\lambda = 0$, i.e., α is an extended $\mathcal{O}$ -operator of weight 0 with extension β of mass (κ, μ) , then $\alpha - \alpha^{21} \in (\mathfrak{g} \ltimes_{\pi^*} \mathfrak{k}^*) \otimes (\mathfrak{g} \ltimes_{\pi^*} \mathfrak{k}^*)$ is a skew-symmetric solution of GCYBE.

- ① Let $(\mathfrak{k}, \pi)$ be a $\mathfrak{g}$ -Lie algebra. Let $\alpha : \mathfrak{k} \rightarrow \mathfrak{g}$ an $\mathcal{O}$ -operator of weight λ . Then $\alpha - \alpha^{21} \in (\mathfrak{g} \ltimes_{\pi^*} \mathfrak{k}^*) \otimes (\mathfrak{g} \ltimes_{\pi^*} \mathfrak{k}^*)$ is a skew-symmetric solution of GCYBE if and only if Eq. (45) and Eq. (46) hold.
- ② Let $\rho : \mathfrak{g} \rightarrow \mathfrak{gl}(V)$ be a representation of $\mathfrak{g}$. Let $\alpha, \beta : \mathfrak{k} \rightarrow \mathfrak{g}$ be two linear maps such that α is an extended $\mathcal{O}$ -operator with extension β of mass κ . Then $\alpha - \alpha^{21} \in (\mathfrak{g} \ltimes_{\rho^*} V^*) \otimes (\mathfrak{g} \ltimes_{\rho^*} V^*)$ is a skew-symmetric solution of GCYBE.

Extensions of CYBE: general algebras

- **Main Idea:**

Let A be an algebra. Then (L, R) is the natural bimodule. Find the dual bimodule of (L, R) . Then with a suitable symmetry, the $\mathcal{O}$ -operator of A associated to the dual bimodule gives the equation of CYBE for A . Finally find the corresponding tensor form.

- **Application:** A solution of CYBE provides a construction (coboundary cases) for a bialgebra structure!

★ Associative algebra $(A, *)$

V.N. Zhelyabin, Jordan bialgebras and their connection with Lie bialgebras, Algebra and Logic **36** (1997) 1-15.

M. Aguiar, On the associative analog of Lie bialgebras, J. Algebra **244** (2001) 492-532.

C. Bai, Double construction of Frobenius algebras, Connes cocycles and their duality, J. Noncommutative Geometry **4** (2010) 475-530.

• **Associative Yang-Baxter equation** (skew-symmetric solution)

$$r_{12} * r_{13} + r_{13} * r_{23} - r_{23} * r_{12} = 0. \quad (46)$$

Associative D -bialgebra (Zhelyabin)

balanced infinitesimal bialgebra (Aguiar)

antisymmetric infinitesimal bialgebra (Bai)

Extensions of CYBE: general algebras

- ★ Dendriform algebra $(A, \succ, \prec)$
- **D-equation** (symmetric solution)

$$r_{12} * r_{13} = r_{13} \prec r_{23} + r_{23} \succ r_{12}, \quad (47)$$

where $x * y = x \prec y + x \succ y$.

Dendriform D-bialgebra

- ★ Quadri-algebra $(A, \searrow, \nearrow, \swarrow, \swarrow)$
- **Q-equation** (skew-symmetric solution)

$$r_{13} \succ r_{23} = r_{23} \nearrow r_{12} + r_{23} \swarrow r_{12} + r_{12} \swarrow r_{13}, \quad (48)$$

$$r_{13} \prec r_{23} = -r_{23} \nearrow r_{12} - r_{12} \searrow r_{13} - r_{12} \swarrow r_{13}, \quad (49)$$

where $x \succ y = x \nearrow y + x \searrow y$, $x \prec y = x \swarrow y + x \swarrow y$.

Quadri-bialgebra

Associative analogues of the study on (extended) $\mathcal{O}$ -operators,
(extended) CYBE and related algebras:

*C. Bai, L. Guo and X. Ni, $\mathcal{O}$ -operators on associative algebras
and associative Yang-Baxter equations, arXiv:0910.3261.*

*C. Bai, L. Guo and X. Ni, $\mathcal{O}$ -operators on associative algebras
and dendriform algebras, arXiv: 1003.2432.*

★ Left-symmetric Lie algebra $(A, \circ)$

C. Bai, Left-symmetric bialgebras and an analogy of the classical Yang-Baxter equation, Comm. Contemp. Math. 10 (2008) 221-260.

• **S-equation** (symmetric solution)

$$-r_{12} \circ r_{13} + r_{12} \circ r_{23} + [r_{13}, r_{23}] = 0. \quad (50)$$

left-symmetric bialgebra

Extensions of CYBE: general algebras

★ Jordan algebra $(A, \circ)$

V.N. Zhelyabin, On a class of Jordan D-bialgebras, St. Petersburg Math. J. 11 (2000) 589-609.

• **Jordan Yang-Baxter equation** (skew-symmetric solution)

$$r_{12} \circ r_{13} + r_{13} \circ r_{23} - r_{12} \circ r_{23} = 0. \quad (51)$$

Jordan D-bialgebra

★ Pre-Jordan algebra $(A, \cdot)$

D. Hou, X. Ni, C. Bai, Pre-Jordan algebras, appear in Mathematica Scandinavica.

D. Hou, C. Bai, Jordan D-bialgebras and pre-Jordan bialgebras, preprint.

• **JP-equation** (symmetric solution)

$$r_{13} \circ r_{23} - r_{12} \cdot r_{23} - r_{12} \cdot r_{13} = 0, \quad (52)$$

where $x \circ y = x \cdot y + y \cdot x$.

pre-Jordan bialgebra

- ① We have been trying to give an operadic interpretation on the study of classical Yang-Baxter equation, its analogues and extensions, bialgebra structures and related structures.
C. Bai, L. Guo, X. Ni, in preparation.
- ② It is natural to consider the possible “quantized” structures.
No idea yet!

Thank You!