# A certificate for semidefinite relaxations in computing positive-dimensional real radical ideals 

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## A R T I C L E I N F O

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#### Abstract

For an ideal $I$ with a positive-dimensional real variety $V_{\mathbb{R}}(I)$, based on moment relaxations, we study how to compute a Pommaret basis which is simultaneously a Gröbner basis of an ideal $J$ generated by the kernel of a truncated moment matrix and satisfying $I \subseteq J \subseteq I\left(V_{\mathbb{R}}(I)\right)$, $V_{\mathbb{R}}(I)=V_{\mathbb{C}}(J) \cap \mathbb{R}^{n}$. We provide a certificate consisting of a condition on coranks of moment matrices for terminating the algorithm. For a generic $\delta$-regular coordinate system, we prove that the condition is satisfiable in a large enough order of moment relaxations.


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## 1. Introduction

Finding real solutions of a polynomial system is a classical mathematical problem with wide applications. Let $I=\left\langle h_{1}, \ldots, h_{m}\right\rangle \subseteq \mathbb{R}[x]:=\mathbb{R}\left[x_{1}, \ldots, x_{n}\right]$ be an ideal generated by polynomials $h_{1}, \ldots, h_{m} \in \mathbb{R}[x]$. Its complex and real algebraic varieties are defined as

$$
V_{\mathbb{C}}(I):=\left\{x \in \mathbb{C}^{n} \mid f(x)=0 \forall f \in I\right\}, \quad V_{\mathbb{R}}(I):=V_{\mathbb{C}}(I) \cap \mathbb{R}^{n}
$$

The vanishing ideal of a set $V \subseteq \mathbb{C}^{n}$ is an ideal

$$
I(V):=\{f \in \mathbb{C}[x] \mid f(v)=0, \forall v \in V\}
$$

The radical (also called complex radical) of $I$ is

[^0]$$
\sqrt{I}:=\left\{f \in \mathbb{C}[x] \mid f^{k} \in I \text { for some } k \in \mathbb{N}\right\},
$$
while the real radical of $I$ is defined as
$$
\sqrt[\mathbb{R}]{I}:=\left\{f \in \mathbb{R}[x] \mid f^{2 k}+\sum_{i=1}^{r} q_{i}^{2} \in I \text { for some } k \in \mathbb{N}, q_{1}, \ldots, q_{r} \in \mathbb{R}[x]\right\} .
$$

Clearly, they satisfy the inclusion $I \subseteq \sqrt{I} \subseteq \sqrt[\mathbb{R}]{I}$. An ideal $I$ is called radical (resp. real radical) if $I=$ $\sqrt{I}$ (resp. $I=\sqrt[\mathbb{R}]{I}$ ). According to the Real Nullstellensatz (Bochnak et al., 1998), the vanishing ideal $I\left(V_{\mathbb{R}}(I)\right)$ of the zero set $V_{\mathbb{R}}(I)$ is a real radical ideal and $I\left(V_{\mathbb{R}}(I)\right)=\sqrt[\mathbb{R}]{I}$.

There exist numerical algorithms (Janovitz-Freireich et al., 2012; Lasserre et al., 2009a, 2009b) and symbolic algorithms (Becker and Wörmann, 1996; Gianni et al., 1988) for computing the radical ideal of a zero-dimensional ideal $I$. For the general case of $I$ being positive-dimensional, a commonly used technique is to reduce the problem to the zero-dimensional case, like in Gianni et al. (1988) and Krick and Logar (1991).

The problem of computing the real radical ideal $\sqrt[\mathbb{R}]{I}$ is typically much more difficult than computing $\sqrt{I}$. Becker and Neuhaus (1993) proposed a symbolic algorithm based on the primary decomposition to compute $\sqrt[\mathbb{R}]{I}$ (see also Neuhaus, 1998; Silke, 2007a; Xia and Yang, 2002; Zeng, 1999). Some interesting algorithms based on critical point methods were proposed in Aubry et al. (2002), Bank et al. (2001), Basu et al. (1997), Safey El Din and Schost (2003) to compute a point on each semi-algebraically connected component of real algebraic varieties.

A new approach based on moment relaxations has been proposed by Lasserre et al. (2013, 2009a, 2009b), Laurent and Rostalski (2010) for computing $\sqrt[\mathbb{R}]{I}$ when $I$ has a zero-dimensional real variety. Hereby we briefly describe this interesting approach.

For a sequence $y=\left(y_{\alpha}\right)_{\alpha \in \mathbb{N}^{n}} \in \mathbb{R}^{\mathbb{N}^{n}}$, its moment matrix

$$
M(y):=\left(y_{\alpha+\beta}\right)_{\alpha, \beta \in \mathbb{N}^{n}}
$$

is a real symmetric matrix whose rows and columns are indexed by the set $\mathbb{T}^{n}:=\left\{\chi^{\alpha} \mid \alpha \in \mathbb{N}^{n}\right\}$ of monomials. Given a polynomial $h \in \mathbb{R}[x]$, we $\operatorname{set} \operatorname{vec}(h):=\left(h_{\alpha}\right)_{\alpha \in \mathbb{N}^{n}}$ and define the sequence $h y:=M(y) \operatorname{vec}(h) \in \mathbb{R}^{\mathbb{N}^{n}}$. We say that a polynomial $p$ lies in the kernel of $M(y)$ when $M(y) p:=$ $M(y) \operatorname{vec}(p)=0$. Given a truncated moment sequence $y=\left(y_{\alpha}\right)_{\alpha \in \mathbb{N}_{2 t}^{n}} \in \mathbb{R}^{\mathbb{N}}{ }^{n}$, it defines a truncated moment matrix

$$
M_{t}(y):=\left(y_{\alpha+\beta}\right)_{\alpha, \beta \in \mathbb{N}_{t}^{n}}
$$

indexed by the set $\mathbb{T}_{t}^{n}:=\left\{\chi^{\alpha} \mid \alpha \in \mathbb{N}_{t}^{n}\right.$ with $\left.|\alpha|:=\sum_{i=1}^{n} \alpha_{i} \leq t\right\}$.
We work with the space $\mathbb{R}[x]_{t}$ of polynomials of the degree smaller than or equal to $t$. For a polynomial $p \in \mathbb{R}[x]_{t}$, if $M_{t}(y) \operatorname{vec}(p)=0$, we say $p$ lies in the kernel of $M_{t}(y)$, i.e.,

$$
\begin{equation*}
\operatorname{ker} M_{t}(y):=\left\{p \in \mathbb{R}[x]_{t} \mid M_{t}(y) \operatorname{vec}(p)=0\right\} . \tag{1}
\end{equation*}
$$

Let $I=\left\langle h_{1}, \ldots, h_{m}\right\rangle \subseteq \mathbb{R}[x]$ be an ideal and set

$$
\begin{equation*}
d_{j}:=\left\lceil\operatorname{deg}\left(h_{j}\right) / 2\right\rceil, \quad d:=\max _{1 \leq j \leq m} d_{j} . \tag{2}
\end{equation*}
$$

For $t \geq d$, we define the set

$$
\begin{equation*}
\mathcal{K}_{t}:=\left\{y \in \mathbb{R}^{\mathbb{N}_{2 t}^{n}} \mid y_{0}=1, M_{t}(y) \succeq 0, M_{t-d_{j}}\left(h_{j} y\right)=0, j=1, \ldots, m\right\} . \tag{3}
\end{equation*}
$$

An element $y \in \mathcal{K}_{t}$ is generic if $M_{t}(y)$ has maximum rank over $\mathcal{K}_{t}$. We denote

$$
\begin{equation*}
\mathcal{K}_{t}^{\text {gen }}:=\left\{y \in \mathcal{K}_{t} \mid \operatorname{rank} M_{t}(y) \text { is maximum over } \mathcal{K}_{t}\right\} . \tag{4}
\end{equation*}
$$

When the real algebraic variety $V_{\mathbb{R}}(I)$ is finite, Lasserre et al. (2008) used the flat extension (a rank condition of moment matrices in Curto and Fialkow (1996)) as a certificate to check whether polynomials in $\operatorname{ker} M_{s}(y)(1 \leq s \leq t)$ for a generic element $y \in \mathcal{K}_{t}$ generate the real radical ideal $I\left(V_{\mathbb{R}}(I)\right)$. When $V_{\mathbb{R}}(I)$ is positive-dimensional, this certificate does not work. The following example given by Fialkow (2011, Example 3.2) can be used to explain the difficulty.

Example 1. Consider $M_{3}(y)$ defined by

$$
M_{3}(y)=\left(\begin{array}{cccccccccc}
1 & 0 & 0 & 1 & 2 & 5 & 0 & 0 & 0 & x \\
0 & 1 & 2 & 0 & 0 & 0 & 2 & 5 & 14 & 42 \\
0 & 2 & 5 & 0 & 0 & x & 5 & 14 & 42 & 132 \\
1 & 0 & 0 & 2 & 5 & 14 & 0 & 0 & x & 0 \\
2 & 0 & 0 & 5 & 14 & 42 & 0 & x & 0 & 0 \\
5 & 0 & x & 14 & 42 & 132 & x & 0 & 0 & 0 \\
0 & 2 & 5 & 0 & 0 & x & 5 & 14 & 42 & 132 \\
0 & 5 & 14 & 0 & x & 0 & 14 & 42 & 132 & r \\
0 & 14 & 42 & x & 0 & 0 & 42 & 132 & r & s \\
x & 42 & 132 & 0 & 0 & 0 & 132 & r & s & t
\end{array}\right) .
$$

With an ordering on the variables $x_{1} \prec x_{2}$, we use the graded reverse lexicographic order (Definition 2) in assigning orders of monomials $x_{1}^{\alpha_{1}} x_{2}^{\alpha_{2}}, 0 \leq \alpha_{1}+\alpha_{2} \leq 3$ and sorting rows and columns of the moment matrix $M_{3}(y)$. When $x=0, r=429, s=1422, t=4798$, we have $M_{3}(y) \succeq 0, \operatorname{rank} M_{3}(y)=9$ and ker $M_{3}(y)=\left\{x_{2}-x_{1}^{3}\right\}$. Unlike the zero-dimensional case, although the kernel of the moment matrix $M_{3}(y)$ consists of only one polynomial $x_{2}-x_{1}^{3}$ which is already a Gröbner basis of the real radical ideal $I=I\left(V_{\mathbb{R}}(I)\right)=\left\langle x_{2}-x_{1}^{3}\right\rangle$, it has been shown by Fialkow (2011) that the truncated moment sequence $y \in \mathcal{K}_{3}$ cannot be extended to the next order, i.e. $y$ has no representing measure.

The motivation of this paper is to provide a certificate for checking $\left\langle\operatorname{ker} M_{t}(y)\right\rangle=I\left(V_{\mathbb{R}}(I)\right)$ when $V_{\mathbb{R}}(I)$ is positive-dimensional. Unfortunately, we still can not solve this open problem (Laurent and Rostalski, 2010, §2.4.3). However, we provide a certificate (7) based on the geometric involutivity theory (Scott, 2006; Scott et al., 2009; Seiler, 2010) for checking whether we have obtained a weak Pommaret basis (also a Gröbner basis) of an ideal $J=\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle$ satisfying $I \subseteq J \subseteq I\left(V_{\mathbb{R}}(I)\right.$ ) under graded reverse lexicographic order. A (weak) Pommaret basis is a special instance of the Gröbner basis which allows for directly reading off the depth, the projective dimension and the CastelnuovoMumford regularity of a module. When the real algebraic variety $V_{\mathbb{R}}(I)$ is positive-dimensional, we will succeed in all the examples presented in Section 4 in showing that the computed basis is a Pommaret basis of the real radical ideal $I\left(V_{\mathbb{R}}(I)\right)$. In general, it is still not possible to prove that the kernel of the moment matrix satisfying the certificate (7) generates a real radical ideal.

The paper is organized as follows. In Section 2, we review some preliminary backgrounds about elementary algebraic geometry, moment matrices, involutive divisions and involutive bases. In Section 3, we propose a certificate for terminating the algorithm and prove that it works for positivedimensional real algebraic varieties under a $\delta$-regular coordinate system. In Section 4, we present computational results for a set of examples taken from Rostalski (2009), Scott et al. (2009), Seiler (2002), Stetter (2004). Some open questions and ongoing work are given in Section 5.

## 2. Preliminaries

We introduce some notation and preliminaries about polynomials, matrices, semidefinite programs and involutive bases. Given $\mathbb{K}=\mathbb{R}$ or $\mathbb{C}$, the ring of multivariate polynomials in $n$ variables over the field $\mathbb{K}$ is denoted by $\mathbb{K}[x]:=\mathbb{K}\left[x_{1}, \ldots, x_{n}\right]$. For an integer $t \geq 0, \mathbb{K}[x]_{t}$ denotes the set of polynomials of degree at most $t$. $\mathbb{N}$ denotes the set of nonnegative integers and we set $\mathbb{N}_{t}^{n}:=\left\{\alpha \in \mathbb{N}^{n} \mid\right.$ $\left.|\alpha|:=\sum_{i=1}^{n} \alpha_{i} \leq t\right\}$ for $t \in \mathbb{N}$. For $\alpha \in \mathbb{N}^{n}, \chi^{\alpha}$ denotes the monomial $\chi_{1}^{\alpha_{1}} \cdots x_{n}^{\alpha_{n}}$ whose total degree is $|\alpha|:=\sum_{i=1}^{n} \alpha_{i}$. All monomials are included in $\mathbb{T}^{n}:=\left\{x^{\alpha} \mid \alpha \in \mathbb{N}^{n}\right\}$ and $\mathbb{T}_{t}^{n}:=\left\{x^{\alpha} \mid \alpha \in \mathbb{N}_{t}^{n}\right\}$ consists of monomials with degrees bounded by $t \in \mathbb{N}$. Consider a polynomial $p \in \mathbb{K}[x], p=\sum_{\alpha \in \mathbb{N}^{n}} p_{\alpha} \chi^{\alpha}$, where there are only finitely many nonzero $p_{\alpha} \in \mathbb{K}$, its leading term $\mathrm{lt}_{<}(p)$ is the maximum term $\chi^{\alpha}$ with respect to a monomial order $\prec$ for which $p_{\alpha} \neq 0$. We denote by $\left\langle\mathrm{lt}_{\prec}(I)\right\rangle$ the ideal generated by leading terms of polynomials in $I$. The symbol $[x]_{t}$ denotes the sequence consisting of all monomials of degree at most $t$ :

$$
[x]_{t}:=\left[1, x_{1}, \cdots, x_{n}, x_{1}^{2}, x_{1} x_{2}, \cdots, x_{1}^{t}, x_{1}^{t-1} x_{2}, \cdots, x_{n}^{t}\right]
$$

### 2.1. Properties of moment matrices

The kernel of a moment matrix is particularly useful as it has the following properties, see Curto and Fialkow (1996), Lasserre et al. (2008), Laurent (2005, 2009), Möller (2004).

Lemma 1. (See Lasserre et al., 2008, Proposition 3.6.) Let $\operatorname{ker} M(y):=\{p \in \mathbb{R}[x] \mid M(y) \operatorname{vec}(p)=0\}$ be the kernel of a moment matrix $M(y)$. Then $\operatorname{ker} M(y)$ is an ideal in $\mathbb{R}[x]$. Moreover, if $M(y) \succeq 0$, then $\operatorname{ker} M(y)$ is a real radical ideal.

The kernel of the truncated moment matrix $M_{t}(y)$ is not an ideal, but under certain conditions, it has the following properties.

Proposition 1. (See Lasserre et al., 2008, Lemma 3.5, 3.9.) Let $y \in \mathbb{R}^{\mathbb{N}_{2 t}^{n}}$ and assume that its truncated moment matrix $M_{t}(y)$ is positive semidefinite.
(i) If $f, g \in \mathbb{R}[x]$ with $\operatorname{deg}(f g) \leq t-1$, then $f \in \operatorname{ker} M_{t}(y) \Longrightarrow f g \in \operatorname{ker} M_{t}(y)$.
(ii) For a polynomial $p \in \mathbb{R}[x]$, if $p^{2 k}+\sigma \in \operatorname{ker} M_{t}(y)$ for some $k \in \mathbb{N}$ and $\sigma \in \sum \mathbb{R}[x]^{2}$, then $p \in \operatorname{ker} M_{t}(y)$.
(iii) We have $\operatorname{ker} M_{t}(y) \cap \mathbb{R}[x]_{s}=\operatorname{ker} M_{s}(y)$ for $1 \leq s \leq t$.

Generic elements of $\mathcal{K}_{t}$ have useful properties. The following results are cited from Lasserre et al., (2008, Lemma 3.1) and Rostalski (2009, Lemmas 7.28, 7.39).

Proposition 2. Assume $y \in \mathcal{K}_{t}^{\text {gen }}$ is generic.
(i) For all $1 \leq s \leq t$, we have $\operatorname{ker} M_{s}(y) \subseteq \sqrt[\mathbb{R}]{I}$ and $\operatorname{ker} M_{s}(y) \subseteq \operatorname{ker} M_{s}(z)$ for all $z \in \mathcal{K}_{t}$.
(ii) If $t \leq t^{\prime}$ and $y^{\prime} \in \mathcal{K}_{t^{\prime}}^{\text {gen }}$, then $\operatorname{ker} M_{t}(y) \subseteq \operatorname{ker} M_{t^{\prime}}\left(y^{\prime}\right)$.
(iii) For every finite basis $\left\{g_{1}, \ldots, g_{k}\right\}$ of the real radical ideal $\sqrt[\mathbb{R}]{I}$, there exists $t_{0} \in \mathbb{N}$ such that $g_{1}, \ldots, g_{k} \in$ $\operatorname{ker} M_{t}(z)$ for all $z \in \mathcal{K}_{t}$ and $t \geq t_{0}$.
(iv) It holds that $\left\langle\operatorname{ker} M_{t}(y)\right\rangle=\sqrt[\mathbb{R}]{I}$ ift is sufficiently large.

### 2.2. Involutive divisions and involutive bases

When the real algebraic variety $V_{\mathbb{R}}(I)$ is zero-dimensional, Lasserre et al. $(2013,2008)$ proposed new approaches based on moment relaxations for computing Gröbner bases or border bases of the real radical ideal $\sqrt[\mathbb{R}]{I}$. For the positive-dimensional real variety $V_{\mathbb{R}}(I)$, we can also compute its Gröbner bases. Stimulated by the work in Lasserre et al. (2009a) and Reid and Zhi (2009), Scott (2006), Scott et al. (2009), we propose a new approach based on the completion to involution to compute a Pommaret basis of an ideal nested between $I$ and $\sqrt[\mathbb{R}]{I}$. A Pommaret basis is automatically a Gröbner basis for the given term order. It contains extra information such as the Castelnuovo-Mumford regularity. Moreover, we provide a new stopping criterion for the algorithm which is based on the classical Cartan's test for involution from the theory of exterior differential systems. We now introduce some basic concepts from the classical theory of involutive systems for polynomial systems. For background, see Seiler $(2002,2010)$.

Definition 1. Let $v=\left[\nu_{1}, \ldots, v_{n}\right] \in \mathbb{N}^{n}$ be the multi index of a monomial $x^{\nu}$. If $k$ is the smallest value such that $v_{k} \neq 0$, then the class of $v$ or $x^{\nu}$ is $k$, written $\operatorname{bys} \operatorname{cls}(\nu)=k$ or $\operatorname{cls}\left(x^{\nu}\right)=k$. The class of a


We say that a term order respects classes, if for monomials $x^{\mu}$ and $x^{\nu}$ of the same total degree, $\operatorname{cls}(\mu)<\operatorname{cls}(\nu)$ implies $x^{\mu}<x^{\nu}$. An important example of a class respecting ordering is the graded reverse lexicographic order $\prec_{\text {tdeg }}$.

Definition 2. With an ordering on the variables $x_{1} \prec \cdots \prec x_{n}$, the graded reverse lexicographic order $\prec_{\text {tdeg }}$ is defined by $\chi^{\alpha} \prec_{\text {tdeg }} x^{\beta}$, if $|\alpha|<|\beta|$, or $|\alpha|=|\beta|$ and the first non-vanishing entry of the multi index $\alpha-\beta$ is positive.

Throughout the paper, we use $\prec_{\text {tdeg }}$ in assigning orders of monomials, and sorting rows and columns of a moment matrix $M_{t}(y)$. The set $\mathbb{N}^{n}$ equipped with the addition is an Abelian monoid. For any multi index $v \in \mathbb{N}^{n}$, we introduce its cone $\mathcal{C}(\nu)=v+\mathbb{N}^{n}$, i.e. the set of all multi indices that can be reached from $\nu$ by adding another multi index. We say that $\nu$ divides $\mu$, written $\nu \mid \mu$ if $\mu \in \mathcal{C}(\nu)$.

Definition 3. (See Seiler, 2010, Definition 3.1.1.) An involutive division $L$ is defined on the monoid $\left(\mathbb{N}^{n},+\right)$. For any finite subset $\mathcal{B} \subseteq \mathbb{N}^{n}$ and any $\nu \in \mathbb{N}^{n}$, we are given a set $N_{L, \mathcal{B}}(\nu) \subseteq\{1, \ldots, n\}$ and the corresponding set $L(\nu, \mathcal{B})=\left\{\mu \in \mathbb{N}^{n} \mid \forall j \notin N_{L, \mathcal{B}}(\nu): \mu_{j}=0\right\}$, which is a submonoid of $\mathbb{N}^{n}$. Moreover the following two conditions on the involutive cones $\mathcal{C}_{L, \mathcal{B}}(\nu)=v+L(\nu, \mathcal{B}) \subseteq \mathbb{N}^{n}$ must hold:
(i) If $\mathcal{C}_{L, \mathcal{B}}(\mu) \cap \mathcal{C}_{L, \mathcal{B}}(\nu) \neq \emptyset$ for some $\mu, v \in \mathcal{B}$, then $\mathcal{C}_{L, \mathcal{B}}(\mu) \subseteq \mathcal{C}_{L, \mathcal{B}}(v)$ or $\mathcal{C}_{L, \mathcal{B}}(v) \subseteq \mathcal{C}_{L, \mathcal{B}}(\mu)$.
(ii) If $\mathcal{B}^{\prime} \subset \mathcal{B}$, then $N_{L, \mathcal{B}}(\nu) \subseteq N_{L, \mathcal{B}^{\prime}}(v)$ for all $v \in \mathcal{B}^{\prime}$.

An arbitrary multi index $\mu \in \mathbb{N}^{n}$ is involutively divisible by $v \in \mathcal{B}$, written $\left.v\right|_{L, \mathcal{B}} \mu$, if $\mu \in \mathcal{C}_{L, \mathcal{B}}(\nu)$. In this case $v$ is called an involutive divisor of $\mu$.

Definition 4. (See Seiler, 2010, Example 3.1.7.) The Pommaret division $L$ is defined by assigning the multiplicative indices $N_{L, \mathcal{B}}(\nu)$ according to a simple rule: if $\operatorname{cls}(\nu)=k$, then we set $N_{L, \mathcal{B}}(\nu)=$ $\{1, \ldots, k\}$.

Remark 1. The Pommaret division is a globally defined division as the assignment of the multiplicative indices to a multi index $v \in \mathcal{B}$ is independent of the set $\mathcal{B}$. The Pommaret division is an involutive division by Seiler (2010, Lemma 3.1.8).

Definition 5. (See Seiler, 2010, Definition 3.1.9.) The involutive span of a finite set $\mathcal{B} \subset \mathbb{N}^{n}$ is

$$
\begin{equation*}
\langle\mathcal{B}\rangle_{L}=\bigcup_{\nu \in \mathcal{B}} \mathcal{C}_{L, \mathcal{B}}(\nu) \tag{5}
\end{equation*}
$$

The set $\mathcal{B}$ is called weakly involutive for the division $L$ or a weak involutive basis of the monoid ideal $\langle\mathcal{B}\rangle$, if $\langle\mathcal{B}\rangle_{L}=\langle\mathcal{B}\rangle$. The set $\mathcal{B}$ is a strong involutive basis or for short an involutive basis, if the union (5) is disjoint, i.e., the intersections of the involutive cones are empty.

For a polynomial $f \in \mathbb{K}[x]$ and a term order $\prec$, we select its leading term $\mathrm{lt}_{\prec}(f)=x^{\mu}$ with the leading exponent $\mathrm{le}_{\prec}(f)=\mu$.

Definition 6. (See Seiler, 2010, Definition 3.4.1.) Let $I \subseteq \mathbb{K}[x]$ be an ideal. A finite set $\mathcal{H} \subset I$ is a weak involutive basis of $I$ for an involutive division $L$ on $\mathbb{N}^{n}$, if $\mathrm{le}_{\prec}(\mathcal{H})$ is a weak involutive basis of the monoid ideal $\mathrm{le}_{\prec}(I)$. The set $\mathcal{H}$ is an involutive basis of $I$, if $\mathrm{le}_{\prec}(\mathcal{H})$ is an involutive basis of le ${ }_{\prec}(I)$ and two distinct elements of $\mathcal{H}$ never possess the same leading exponents.

Not every ideal in $\mathbb{K}[x]$ possesses a finite Pommaret basis (see Seiler, 2010).

Definition 7. (See Seiler, 2010, Definition 4.3.1.) A coordinate system is called $\delta$-regular for the ideal $I \subseteq \mathbb{K}[x]$ and the term order $\prec$, if $I$ possesses a finite Pommaret basis for the term order $\prec$.

Theorem 1. (See Seiler, 2010, Theorem 4.3.15.) Every polynomial ideal $I \subseteq \mathbb{K}[x]$ possesses a finite Pommaret basis for a term order $\prec$ in some suitably chosen coordinate systems.

Definition 8. (See Seiler, 2010, Definition 3.4.2.) Let $\mathcal{F} \subset \mathbb{K}[x] \backslash\{0\}$ be a finite set of polynomials and $L$ be an involutive division on $\mathbb{N}^{n}$. We assign to each element $f \in \mathcal{F}$ a set of multiplicative variables

$$
X_{L, \mathcal{F}, \prec}(f)=\left\{x_{i} \mid i \in N_{L, \mathrm{l}_{<} \mathcal{F}}\left(\mathrm{le}_{\prec} f\right)\right\} .
$$

The involutive span of $\mathcal{F}$ is then the set

$$
\langle\mathcal{F}\rangle_{L, \prec}=\sum_{f \in \mathcal{F}} \mathbb{K}\left[X_{L, \mathcal{F}, \prec}(f)\right] \cdot f \subseteq\langle\mathcal{F}\rangle .
$$

Theorem 2. (See Seiler, 2010, Theorem 3.4.4.) Let $I \subseteq \mathbb{K}[x]$ be a nonzero ideal, $\mathcal{H} \subset I \backslash\{0\}$ a finite set and $L$ an involutive division on $\mathbb{N}^{n}$. Then the following two statements are equivalent.
(i) The set $\mathcal{H} \subset I$ is a weak involutive basis of I with respect to $L$ and $\prec$.
(ii) Every polynomial $f \in I$ can be written in the form

$$
\begin{equation*}
f=\sum_{h \in \mathcal{H}} P_{h} \cdot h \tag{6}
\end{equation*}
$$

with coefficients $P_{h} \in \mathbb{K}\left[X_{L, \mathcal{H}, \prec}(h)\right]$ satisfying $\mathrm{lt}_{\prec}\left(P_{h} \cdot h\right) \preceq \mathrm{lt}_{\prec}(f)$ for all polynomials $h \in \mathcal{H}$ such that $P_{h} \neq 0$.
$\mathcal{H}$ is an involutive basis, if and only if the representation (6) is unique.
Remark 2. Definition 5, Definition 6 and the representation (6) in Theorem 2 imply immediately that any weak involutive basis is a Gröbner basis.

Corollary 1. (See Seiler, 2010, Corollary 3.4.5.) Let $\mathcal{H}$ be a weak involutive basis of the ideal $I \subseteq \mathbb{K}[x]$. Then $\langle\mathcal{H}\rangle_{L,<}=I$. If $\mathcal{H}$ is even an involutive basis of I, then I considered as a $\mathbb{K}$-linear space possesses a direct sum decomposition $I=\bigoplus_{h \in \mathcal{H}} \mathbb{K}\left[X_{L, \mathcal{H}, \prec}(h)\right] \cdot h$.

Proposition 3. (See Seiler, 2010, Proposition 3.4.7.) Let $I \subseteq \mathbb{K}[x]$ be an ideal and $\mathcal{H} \subset I$ be a weak involutive basis of I for the involutive division $L$. Then there exists a subset $\mathcal{H}^{\prime} \subseteq \mathcal{H}$ which is an involutive basis of $I$.

Definition 9. If we regard $\mathbb{K}[x]$ as a linear space, then the ideal $I$ and the truncated ideal $I_{t}=I \cap \mathbb{K}[x]_{t}$ are both subspaces in $\mathbb{K}[x]$. We say that the set $G=\left\{g_{1}, \ldots, g_{s}\right\}$ is a reduced basis of $I_{t}$, if it is a linear independent basis of $I_{t}$ and all polynomials in $G$ have different leading monomials with respect to a given term order.

## 3. Computing a pommaret basis

In this section, we present an algorithm as well as a certificate for computing a Pommaret basis for an ideal $J$, s.t. $I \subseteq J \subseteq I\left(V_{\mathbb{R}}(I)\right)$ when $V_{\mathbb{R}}(I)$ is positive-dimensional.

### 3.1. The certificate

Let $I=\left\langle h_{1}, \ldots, h_{m}\right\rangle \subseteq \mathbb{R}[x]$ be an ideal and $d:=\max _{1 \leq j \leq m} d_{j}, d_{j}:=\left\lceil\operatorname{deg}\left(h_{j}\right) / 2\right\rceil$. For each $t \geq d$, recall the notions

$$
\mathcal{K}_{t}:=\left\{y \in \mathbb{R}^{\mathbb{N}_{2 t}^{n}} \mid y_{0}=1, M_{t}(y) \succeq 0, M_{t-d_{j}}\left(h_{j} y\right)=0, j=1, \ldots, m\right\},
$$

and

$$
\mathcal{K}_{t}^{\text {gen }}:=\left\{y \in \mathcal{K}_{t} \mid \operatorname{rank} M_{t}(y) \text { is maximum over } \mathcal{K}_{t}\right\} .
$$

For a moment matrix $M_{t}(y)$ of order $t$, the truncated moment matrix $M_{t-\ell}(y)$ for $\ell<t$ is the order $t-\ell$ principal submatrix of $M_{t}(y)$ indexed by $\alpha, \beta \in \mathbb{N}_{t-\ell}^{n}$.

Let $\alpha_{j}$ denote the number of class $j$ polynomials of degree $t-2$ exactly in a reduced basis of $\operatorname{ker} M_{t-2}(y)$. Although the reduced bases of $\operatorname{ker} M_{t-2}(y)$ are not unique, they have the same set of leading terms since they can be represented linearly by each other. Therefore, the quantity $\sum_{j=1}^{n} j \alpha_{j}$ does not depend on the choice of the reduced basis of $\operatorname{ker} M_{t-2}(y)$. Moreover, according to Proposition 1, $\operatorname{ker} M_{t}(y) \cap \mathbb{R}[x]_{s}=\operatorname{ker} M_{s}(y)$ for $1 \leq s \leq t$, at Step 2 of Algorithm 1, a reduced basis of $\operatorname{ker} M_{t-2}(y)$ is obtained by selecting all polynomials of degree at most $t-2$ in a reduced basis of $\operatorname{ker} M_{t-1}(y)$.

Theorem 3. Let $I=\left\langle h_{1}, \ldots, h_{m}\right\rangle \subseteq \mathbb{R}[x]$ be an ideal. Consider an integer $t \geq 2 d$ and let $y$ be a generic element of $\mathcal{K}_{t}^{\text {gen }}$. Assume that the following relation

$$
\begin{equation*}
\sum_{j=1}^{n} j \alpha_{j}=\operatorname{corank} M_{t-1}(y)-\operatorname{corank} M_{t-2}(y) \tag{7}
\end{equation*}
$$

holds. Then a reduced basis of the null space of $M_{t-2}(y)$ is a weak Pommaret basis for $J=\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle$ under the monomial ordering $\prec_{\text {tdeg }}$ and

$$
\begin{equation*}
I \subseteq J \subseteq I\left(V_{\mathbb{R}}(I)\right), \quad V_{\mathbb{R}}(I)=V_{\mathbb{C}}(J) \cap \mathbb{R}^{n} \tag{8}
\end{equation*}
$$

The proof of Theorem 3 follows from Proposition 2 and Theorem 4 whose proofs are given in Section 3.3.

In our algorithm, we need to find an element $y$ in $\mathcal{K}_{t}$ maximizing the rank of $M_{t}(y)$. As pointed out in Lasserre et al. (2008), this could be done typically by solving the semidefinite program

$$
\begin{equation*}
\min \quad 0 \quad \text { s.t. } \quad y \in \mathcal{K}_{t} \tag{9}
\end{equation*}
$$

with interior-point algorithms using self-dual embedding, see Vandenberghe and Boyd (1996), Wolkowicz et al. (2000).

### 3.2. An algorithm for computing a Pommaret basis

We list the main steps of our algorithm based on solving (9) for computing a Pommaret basis of the ideal $J=\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle$ nested between $I$ and $I\left(V_{\mathbb{R}}(I)\right)$.

Algorithm 1. Computing a Pommaret basis of an ideal $J$ such that $I \subseteq J \subseteq I\left(V_{\mathbb{R}}(I)\right)$.
Input: A set of polynomials $\left\{h_{1}, \ldots, h_{m}\right\}$ generating I and the monomial ordering $<_{\text {tdeg }}$ on variables $x_{1}, \ldots, x_{n}$.

Output: A Pommaret basis for $\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle$ under the monomial ordering $<_{\text {tdeg }}$.
Step 1 For $t \geq 2 d$, compute a generic element $y \in \mathcal{K}_{t}$ by solving (9).
Step 2 Compute a reduced basis of $\operatorname{ker} M_{t-1}(y)$.

- A reduced basis $\left\{g_{1}, \ldots, g_{s+r}\right\}$ of $\operatorname{ker} M_{t-2}(y)$ is obtained by choosing all polynomials of degree at most $t-2$ in the reduced basis of $\operatorname{ker} M_{t-1}(y)$, where $\operatorname{deg}\left(g_{i}\right)=t-2$ for $1 \leq i \leq s$ and $\operatorname{deg}\left(g_{i}\right)<t-2$ for $s+1 \leq i \leq s+r$.
- Compute the value of $\sum_{j=1}^{n} j \alpha_{j}$, where $\alpha_{j}$ counts the number of class $j$ polynomials in $\left\{g_{1}, \ldots, g_{s}\right\}$.
Step 3 Compute corank $M_{t-1}(y)-\operatorname{corank} M_{t-2}(y)$ by calculating the number of polynomials of degree $t-1$ in the reduced basis of $\operatorname{ker} M_{t-1}(y)$.
Step 4 Test whether the condition (7) is satisfied.
- If yes, then $\left\{g_{1}, \ldots, g_{s+r}\right\}$ is a weak Pommaret basis for $\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle$ and can be reduced further to a Pommaret basis.
- Otherwise, let $t:=t+1$ and go to Step 1.

In Section 3.3, we prove that Algorithm 1 is correct and terminates in a finite number of steps in a $\delta$-regular coordinate system for $\sqrt[\mathbb{R}]{I}$. The algorithm has been implemented in Matlab using the GloptiPoly toolbox (Henrion and Lasserre, 2003) and we demonstrate its performance on a set of examples given in Section 4.

### 3.3. Justification of the certificate

Our main goal in this section is to prove that Algorithm 1 is correct and it terminates after a finite number of steps in a $\delta$-regular coordinate system for $\sqrt[\mathbb{R}]{I}$.

Assumption 1. Let $I=\left\langle h_{1}, \ldots, h_{m}\right\rangle \subseteq \mathbb{R}[x]$ be an ideal. Suppose there exists an integer $t \geq 2 d$ satisfying the condition (7) for $y \in \mathcal{K}_{t}^{\text {gen }}$. Let $\left\{g_{1}, \ldots, g_{s+r}\right\}$ be a reduced basis of ker $M_{t-2}(y)$, where

$$
\operatorname{deg}\left(g_{i}\right)=t-2 \quad \text { for } 1 \leq i \leq s, \quad \text { and } \quad \operatorname{deg}\left(g_{i}\right)<t-2 \quad \text { for } s+1 \leq i \leq s+r .
$$

Lemma 2. Under Assumption 1, the polynomial set

$$
\left\{x_{1} g_{1}, \ldots, x_{j_{1}} g_{1}, \ldots, x_{1} g_{s}, \ldots, x_{j_{s}} g_{s}, g_{1}, \ldots, g_{s+r}\right\}
$$

is a reduced basis of $\operatorname{ker} M_{t-1}(y)$, where $j_{i}=\operatorname{cls}\left(g_{i}\right)$ for $i=1, \ldots, s$.
Proof. For $k=1, \ldots, n, i=1, \ldots, s+r$, since $\operatorname{deg}\left(x_{k} g_{i}\right) \leq t-1$, by Proposition 1(i), we have $x_{k} g_{i} \in$ $\operatorname{ker} M_{t-1}(y)$. In fact, since each polynomial in $\left\{g_{1}, \ldots, g_{s+r}\right\}$ has different leading terms, according to Definition 9, the polynomials

$$
\begin{equation*}
x_{1} g_{1}, \ldots, x_{j_{1}} g_{1}, \ldots, x_{1} g_{s}, \ldots, x_{j_{s}} g_{s} \tag{10}
\end{equation*}
$$

all have distinct leading terms of degree $t-1$. Hence they are linearly independent. Suppose there are $\alpha_{j}$ polynomials of class $j$ in $\left\{g_{1}, \ldots, g_{s}\right\}$, then polynomials in (10) yield $\sum_{j=1}^{n} j \alpha_{j}$ linearly independent polynomials of degree $t-1$ in $\operatorname{ker} M_{t-1}(y)$. On the other hand, the number of linearly independent polynomials of degree $t-1$ in a reduced basis of $\operatorname{ker} M_{t-1}(y)$ equals to corank $M_{t-1}(y)-\operatorname{corank} M_{t-2}(y)$. Hence, the condition (7) and Proposition 1(iii) imply that the conclusion is true.

Remark 3. Under Assumption 1, for any polynomial $f \in \operatorname{ker} M_{t-1}(y)$, we can express it as a linear combination:

$$
\begin{equation*}
f=\sum_{k=1}^{s} \sum_{i=1}^{\operatorname{cls}\left(g_{k}\right)} c_{i k} x_{i} g_{k}+\sum_{k=1}^{s+r} \lambda_{k} g_{k}, \tag{11}
\end{equation*}
$$

 $\mathrm{lt}_{<}(f)$ for $1 \leq k \leq s+r$. Note that every polynomial in $\left\{x_{1} g_{1}, \ldots, x_{j_{1}} g_{1}, \ldots, x_{1} g_{s}, \ldots, x_{j_{s}} g_{s}, g_{1}, \ldots\right.$, $\left.g_{s+r}\right\}$ has a different leading term. Under the graded monomial ordering $<_{\text {tdeg }}$, there is only one $c_{i_{0} k_{0}} \neq 0$ with $\mathrm{lt}_{<}\left(x_{i_{0}} g_{k_{0}}\right)=\operatorname{lt}_{<}(f)$ if not all $c_{i k}$ are zeros. If all $c_{i k}$ are zero, then there exists only one index $1 \leq k \leq s+r$ such that $\lambda_{k} \neq 0$ and $\mathrm{lt}_{<}\left(g_{k}\right)=\mathrm{lt}_{\prec}(f)$. This property is very important and will be used in the proofs of theorems below.

Lemma 3. Under Assumption 1, for all monomials $x^{\mu}$ and polynomials $g_{j}$ with $\operatorname{deg}\left(g_{j}\right)<t-2, j=s+$ $1, \ldots, s+r$, the polynomial $x^{\mu} g_{j}$ can be expressed as

$$
\begin{equation*}
x^{\mu} g_{j}=\sum_{k=1}^{s} h_{k} g_{k}+\sum_{k=s+1}^{s+r} \lambda_{k} g_{k}, \tag{12}
\end{equation*}
$$

where $h_{k} \in \mathbb{R}[x]$ and $\lambda_{k} \in \mathbb{R}$ satisfying $\mathrm{lt}_{\prec}\left(h_{k} g_{k}\right) \preceq_{\text {tdeg }} \mathrm{It}_{<}\left(x^{\mu} g_{j}\right), k=1, \ldots, s$ and $\mathrm{lt}_{\prec}\left(\lambda_{k} g_{k}\right) \preceq_{\text {tdeg }}$ $\mathrm{lt}_{<}\left(x^{\mu} g_{j}\right), k=s+1, \ldots, s+r$.

Proof. If $\operatorname{deg}\left(x^{\mu} g_{j}\right) \leq t-1$, by Proposition 1(i), we have $x^{\mu} g_{j} \in \operatorname{ker} M_{t-1}(y)$. According to Remark 3, we have the expression (12). Otherwise, we set $x^{\mu}=x^{\mu_{1}} x^{\mu_{2}}$ such that $\operatorname{deg}\left(x^{\mu_{2}} g_{j}\right)=t-1$. Hence, we have

$$
\begin{aligned}
x^{\mu} g_{j} & =x^{\mu_{1}} x^{\mu_{2}} g_{j}=x^{\mu_{1}}\left(\sum_{k=1}^{s} h_{k} g_{k}+\sum_{k=s+1}^{s+r} \lambda_{k} g_{k}\right) \\
& =\sum_{k=1}^{s} x^{\mu_{1}} h_{k} g_{k}+\sum_{k=s+1}^{s+r} \lambda_{k} x^{\mu_{1}} g_{k} .
\end{aligned}
$$

We can repeat the above reduction on $x^{\mu_{1}} g_{k}$ for $s+1 \leq k \leq s+r$. Since $\operatorname{deg}\left(x^{\mu_{1}}\right)<\operatorname{deg}\left(x^{\mu}\right)$, after a finite number of steps, we have the expected form (12).

Theorem 4. Under Assumption 1, a reduced basis $\left\{g_{1}, \ldots, g_{s+r}\right\}$ of $\operatorname{ker} M_{t-2}(y)$ is a weak Pommaret basis of the ideal $\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle$.

Proof. We show that any polynomial $f \in\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle$ can be represented as

$$
\begin{equation*}
f=\sum_{k=1}^{s} h_{k} g_{k}+\sum_{k=s+1}^{s+r} \lambda_{k} g_{k} \tag{13}
\end{equation*}
$$

where $\lambda_{k} \in \mathbb{R}$ and $h_{k} \in \mathbb{R}\left[x_{1}, \ldots, x_{\operatorname{cls}\left(g_{k}\right)}\right]$. Since $\mathrm{lt}_{<}\left(h_{k} g_{k}\right)$ and $\mathrm{lt}_{<}\left(g_{k}\right)$ are all different for $1 \leq k \leq s+r$, if $f$ satisfies (13), then we have $\mathrm{lt}_{<}\left(h_{k} g_{k}\right) \preceq_{\text {tdeg }} \mathrm{It}_{<}(f)$ for $1 \leq k \leq s$ and $\mathrm{lt}_{<}\left(\lambda_{k} g_{k}\right) \preceq_{\text {tdeg }} \mathrm{It}_{<}(f)$ for $s+1 \leq k \leq s+r$. Therefore, according to Theorem 2, the polynomial set $\left\{g_{1}, \ldots, g_{s+r}\right\}$ is a weak Pommaret basis of the ideal $\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle$.

Since $\left\{g_{1}, \ldots, g_{s+r}\right\}$ is a reduced basis of ker $M_{t-2}(y)$, every polynomial $f \in\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle$ can be represented as

$$
f=\sum_{j=1}^{s+r} h_{j} g_{j},
$$

where $h_{j} \in \mathbb{R}[x], j=1, \ldots, s+r$. Hence, we only need to show that each polynomial $x^{\mu} g_{j}$ for $\mu \in \mathbb{N}^{n}$ and $1 \leq j \leq s+r$ can be written as (13).

Set $f=x^{\mu} g_{j}$. If $\operatorname{deg}(f) \leq t-1$, by Lemma 2 , we have the expected expression (13) directly. Otherwise, we prove by the induction on its leading term $\mathrm{lt}_{<}(f)=t_{0}$, i.e., we assume that $f=x^{\mu} g_{j}$ has the expected expression (13) as long as $\mathrm{lt}_{\prec}(f) \prec_{\text {tdeg }} t_{0}$ for $\mu \in \mathbb{N}^{n}$ and $1 \leq j \leq s+r$, we show it has the expected expression when $\mathrm{It}_{<}(f)=t_{0}$.

If $x^{\mu} \in \mathbb{R}\left[x_{1}, \ldots, x_{\operatorname{cls}\left(g_{j}\right)}\right]$, nothing needs to be proved. Otherwise, without loss of generality, let $x_{i_{1}}$ be a non-multiplicative variable in $x^{\mu}$ with respect to $g_{j}$, i.e. $i_{1} \notin\left\{1, \ldots, \operatorname{cls}\left(g_{j}\right)\right\}$. Since $\operatorname{deg}\left(g_{j}\right) \leq t-2$, $j=1, \ldots, s+r$, by Proposition 1(i), we have $x_{i_{1}} g_{j} \in \operatorname{ker} M_{t-1}(y)$. By Lemma 2 and Remark 3, we have

$$
\begin{align*}
f & =x^{\mu} g_{j}=\left(x^{\mu} / x_{i_{1}}\right) x_{i_{1}} g_{j} \\
& =\left(x^{\mu} / x_{i_{1}}\right)\left(\sum_{k=1}^{s} \sum_{i=1}^{\operatorname{cls}\left(g_{k}\right)} c_{i k} x_{i} g_{k}+\sum_{k=1}^{s+r} \lambda_{k} g_{k}\right) \\
& =\sum_{k=1}^{s} \sum_{i=1}^{\operatorname{cls}\left(g_{k}\right)} c_{i k}\left(x^{\mu} / x_{i_{1}}\right) x_{i} g_{k}+\sum_{k=1}^{s+r} \lambda_{k}\left(x^{\mu} / x_{i_{1}}\right) g_{k} . \tag{14}
\end{align*}
$$

According to Remark 3, there are two cases:
(i) if all $c_{i k}=0$, there exists only one $1 \leq j_{1} \leq s+r$, such that $\lambda_{j_{1}} \neq 0$ and $\mathrm{lt}_{<}\left(\lambda_{j_{1}}\left(x^{\mu} / x_{i_{1}}\right) g_{j_{1}}\right)=t_{0}$;
(ii) otherwise, there exist $1 \leq j_{1} \leq s$ and $1 \leq i_{2} \leq \operatorname{cls}\left(g_{j_{1}}\right)$ such that $c_{i_{2} j_{1}} \neq 0$ and $\operatorname{lt}_{\alpha}\left(c_{i_{2} j_{1}}\left(x^{\mu}\right)\right.$ $\left.\left.x_{i_{1}}\right) x_{i_{2}} g_{j_{1}}\right)=t_{0}$.

In both cases, all other terms in (14) have leading terms of order less than $t_{0}$, which can be expressed as (13) by induction. Moreover, above two cases do not exist simultaneously. Therefore, we only need to check whether the polynomial $\lambda_{j_{1}}\left(x^{\mu} / x_{i_{1}}\right) g_{j_{1}}$ in case (i) or $c_{i_{2} j_{1}}\left(x^{\mu} / x_{i_{1}}\right) x_{i_{2}} g_{j_{1}}$ in case (ii) has the representation (13).

In case (i), if $x^{\mu} / x_{i_{1}} \in \mathbb{R}\left[x_{1}, \ldots, x_{\operatorname{cls}\left(g_{j_{1}}\right)}\right]$ then we obtain the representation (13). Otherwise, we repeat the reduction to the polynomial $\left(x^{\mu} / x_{i_{1}}\right) g_{j_{1}}$. Since $\mathrm{lt}_{<}\left(\lambda_{j_{1}}\left(x^{\mu} / x_{i_{1}}\right) g_{j_{1}}\right)=\mathrm{lt}_{<}\left(x^{\mu} g_{j}\right)=t_{0}$, we have $\operatorname{deg}\left(g_{j}\right)<\operatorname{deg}\left(g_{j_{1}}\right)$, i.e.,

$$
\mathrm{lt}_{<}\left(g_{j}\right)<_{\mathrm{tdeg}} \mathrm{lt}_{\prec}\left(g_{j_{1}}\right)
$$

In case (ii), if $x^{\mu} / x_{i_{1}} \in \mathbb{R}\left[x_{1}, \ldots, x_{\mathrm{cls}\left(g_{j_{1}}\right)}\right]$, since $x_{i_{2}}$ is a multiplicative variable of $\mathrm{lt}_{<}\left(g_{j_{1}}\right)$, then $\left(x^{\mu} / x_{i_{1}}\right) x_{i_{2}} \in \mathbb{R}\left[x_{1}, \ldots, x_{\operatorname{cls}\left(g_{j_{1}}\right)}\right]$. Hence, we obtain the representation (13). Otherwise, since $x_{i_{1}}$ is a non-multiplicative variable of $\mathrm{lt}_{<}\left(g_{j}\right)$ and $x_{i_{2}}$ is a multiplicative variable of $\mathrm{lt}_{<}\left(g_{j_{1}}\right)$, we have

$$
\operatorname{cls}\left(g_{j}\right)<\operatorname{cls}\left(x_{i_{1}}\right), \quad \operatorname{cls}\left(x_{i_{2}}\right) \leq \operatorname{cls}\left(g_{j_{1}}\right)
$$

Because $\mathrm{lt}_{<}\left(c_{i_{2} j_{1}}\left(x^{\mu} / x_{i_{1}}\right) x_{i_{2}} g_{j_{1}}\right)=t_{0}$, we have $\mathrm{lt}_{<}\left(x_{i_{2}} g_{j_{1}}\right)=\mathrm{lt}_{<}\left(x_{i_{1}} g_{j}\right)$ and

$$
\begin{equation*}
\operatorname{cls}\left(x_{i_{2}}\right)=\operatorname{cls}\left(x_{i_{2}} g_{j_{1}}\right)=\operatorname{cls}\left(x_{i_{1}} g_{j}\right)<\operatorname{cls}\left(x_{i_{1}}\right) . \tag{15}
\end{equation*}
$$

This implies that $x_{i_{2}} \prec_{\text {tdeg }} x_{i_{1}}$. If $\mathrm{lt}_{\prec}\left(g_{j_{1}}\right) \preceq_{\text {tdeg }} \mathrm{lt}_{\prec}\left(g_{j}\right)$, we have $\mathrm{lt}_{\prec}\left(x_{i_{2}} g_{j_{1}}\right)<_{\text {tdeg }} \mathrm{It}_{\prec}\left(x_{i_{1}} g_{j}\right)$ which leads to a contradiction. Therefore, we can deduce that

$$
\mathrm{lt}_{<}\left(g_{j}\right)<_{\mathrm{tdeg}} \mathrm{lt}_{<}\left(g_{j_{1}}\right) .
$$

In both cases, if the reduction does not stop, we will obtain a sequence of polynomials satisfying

$$
\mathrm{lt}_{\prec}\left(g_{j}\right) \prec_{\text {tdeg }} \mathrm{It}_{\prec}\left(g_{j_{1}}\right) \prec_{\text {tdeg }} \cdots \prec_{\text {tdeg }} \mathrm{It}_{\prec}\left(g_{j_{i}}\right) \prec_{\text {tdeg }} \mathrm{It}_{\prec}\left(g_{j_{i+1}}\right) \prec_{\text {tdeg }} \cdots \prec_{\text {tdeg }} t_{0} .
$$

Since the number of polynomials with strictly increasing leading terms bounded by $\mathrm{lt}_{<}(f)=t_{0}$ is finite, the above procedure will stop in a finite number of steps and we obtain the expected form (13) for $f$.

Theorem 5. In a $\delta$-regular coordinate system for $\sqrt[\mathbb{R}]{I}$, after a finite number of steps, Algorithm 1 will terminate and return an integer $t \geq 2 d$ which satisfies the condition (7) for an element $y \in \mathcal{K}_{t}^{\text {gen }}$.

Proof. In a $\delta$-regular coordinate system, we have a finite Pommaret basis $\mathcal{H}=\left\{h_{1}, \ldots, h_{s}\right\}$ for the real radical ideal $I\left(V_{\mathbb{R}}(I)\right)$. According to Proposition 2(iii), we can conclude that there exists an integer $t_{1}$ such that the Pommaret basis $\left\{h_{1}, \ldots, h_{s}\right\}$ is contained in $\operatorname{ker} M_{t}(y)$ for all $y \in \mathcal{K}_{t}$ and $t \geq t_{1}$.

Since $\mathcal{H}$ is a Pommaret basis of $I\left(V_{\mathbb{R}}(I)\right)$, according to Corollary 1 , for $t \geq t_{1}+2$, we have the following decomposition:

$$
\begin{equation*}
I\left(V_{\mathbb{R}}(I)\right)_{t-2}=\bigoplus_{h_{k} \in \mathcal{H}} \mathbb{R}\left[x_{1}, \ldots, x_{\operatorname{cls}\left(h_{k}\right)}\right]_{t-2-\operatorname{deg}\left(h_{k}\right)} \cdot h_{k} \tag{16}
\end{equation*}
$$

Let

$$
\begin{equation*}
T=\left\{x^{u} h_{k} \mid x^{u} \in \mathbb{R}\left[x_{1}, \ldots, x_{\operatorname{cls}\left(h_{k}\right)}\right], \operatorname{deg}\left(x^{u}\right) \leq t-2-\operatorname{deg}\left(h_{k}\right), 1 \leq k \leq s\right\} . \tag{17}
\end{equation*}
$$

According to Proposition 1(i), $T \subseteq \operatorname{ker} M_{t-2}(y)$. Therefore, by (16) and (17), we have

$$
I\left(V_{\mathbb{R}}(I)\right)_{t-2} \subseteq \operatorname{ker} M_{t-2}(y)
$$

On the other hand, $y$ is a generic element, by Proposition 2(i), we have

$$
\operatorname{ker} M_{t-2}(y) \subseteq I\left(V_{\mathbb{R}}(I)\right)_{t-2}
$$

Hence, we have $\operatorname{ker} M_{t-2}(y)=I\left(V_{\mathbb{R}}(I)\right)_{t-2}$ and the decomposition:

$$
\begin{equation*}
\operatorname{ker} M_{t-2}(y)=\bigoplus_{h_{k} \in \mathcal{H}} \mathbb{R}\left[x_{1}, \ldots, x_{\operatorname{cls}\left(h_{k}\right)}\right]_{t-2-\operatorname{deg}\left(h_{k}\right)} \cdot h_{k} \tag{18}
\end{equation*}
$$

Since $\mathcal{H}$ is a Pommaret basis of $I\left(V_{\mathbb{R}}(I)\right)$, according to Definition 6 , each polynomial in $T$ has a different leading term. Therefore $T$ is actually a reduced basis of ker $M_{t-2}(y)$. By Theorem 3, it suffices to show that the condition (7) holds for the polynomials in $T$.

Similar to the decomposition (18), we can show that there exists a direct sum decomposition of $\operatorname{ker} M_{t-1}(y)$ :

$$
\begin{equation*}
\operatorname{ker} M_{t-1}(y)=\bigoplus_{h_{k} \in \mathcal{H}} \mathbb{R}\left[x_{1}, \ldots, x_{\operatorname{cls}\left(h_{k}\right)}\right]_{t-1-\operatorname{deg}\left(h_{k}\right)} \cdot h_{k} \tag{19}
\end{equation*}
$$

For a polynomial $f \in \operatorname{ker} M_{t-1}(y)$ with $\operatorname{deg}(f)=t-1$, according to (19), we have the following equalities:

$$
\begin{aligned}
f & =\sum_{k=1}^{s} \sum_{0 \leq|\mu| \leq t-1-\operatorname{deg}\left(h_{k}\right)} c_{\mu k} x^{\mu} h_{k} \quad\left(\text { note that } x ^ { \mu } \in \mathbb { R } \left[x_{1}, \ldots, x_{\left.\left.\operatorname{cls}\left(h_{k}\right)\right]\right)}\right.\right. \\
& =\sum_{k=1}^{s} \sum_{|\mu|=t-1-\operatorname{deg}\left(h_{k}\right)} c_{\mu k} x^{\mu} h_{k}+\sum_{k=1}^{s} \sum_{0 \leq|\mu| \leq t-2-\operatorname{deg}\left(h_{k}\right)} c_{\mu k} x^{\mu} h_{k} \\
& =\sum_{k=1}^{s} \sum_{|\mu|=t-1-\operatorname{deg}\left(h_{k}\right)} c_{\mu k} x_{\operatorname{cls}\left(x^{\mu}\right)}\left(x^{\mu} / x_{\operatorname{cls}\left(x^{\mu}\right)}\right) h_{k}+\sum_{k=1}^{s} \sum_{0 \leq|\mu| \leq t-2-\operatorname{deg}\left(h_{k}\right)} c_{\mu k} x^{\mu} h_{k} .
\end{aligned}
$$

Since $x_{\operatorname{cls}\left(x^{\mu}\right)}$ is always a multiplicative variable for the polynomial $\left(x^{\mu} / x_{\operatorname{cls}\left(x^{\mu}\right)}\right) h_{k} \in T$, we know that each polynomial in ker $M_{t-1}(y)$ can be represented by the polynomials in $T$ and $T_{1}$, where

$$
T_{1}=\left\{x_{i} g \mid 1 \leq i \leq \operatorname{cls}(g), g \in T, \operatorname{deg}(g)=t-2\right\}
$$

The polynomials in $T_{1}$ and $T$ have different leading terms, hence $T \cup T_{1}$ is a linearly independent basis of ker $M_{t-1}(y)$. Moreover, $T$ is a reduced basis of $\operatorname{ker} M_{t-2}(y)$, and $T_{1}$ consists of all linearly independent polynomials with degree $t-1$ in $\operatorname{ker} M_{t-1}(y)$. We can deduce that the number of polynomials in $T_{1}$ is equal to corank $M_{t-1}(y)-\operatorname{corank} M_{t-2}(y)$. On the other hand, let $\alpha_{j}$ denote the number of polynomials of class $j$ and degree $t-2$ in $T$. Since the set $T_{1}$ is constructed by multiplying polynomials in $T$ of degree $t-2$ by their multiplicative variables only, the total number of polynomials in $T_{1}$ is equal to $\sum_{j=1}^{n} j \alpha_{j}$. Therefore, the condition (7) is satisfied.

### 3.4. An extension to $I\left(V_{\mathbb{R}}(I) \cap \mathcal{A}\right)$

Consider the semialgebraic set

$$
\begin{equation*}
\mathcal{A}:=\left\{x \in \mathbb{R}^{n} \mid f_{1}(x) \geq 0, \ldots, f_{s}(x) \geq 0\right\} \tag{20}
\end{equation*}
$$

where $f_{1}, \ldots, f_{s} \in \mathbb{R}[x]$. The $\mathcal{A}$-variety $V_{\mathcal{A}}(I)$ denotes the intersection

$$
V_{\mathcal{A}}(I)=V_{\mathbb{R}}(I) \cap \mathcal{A} .
$$

For every $v \in\{0,1\}^{s}$, we denote the product $f^{v}:=f_{1}^{\nu_{1}} f_{2}^{\nu_{2}} \cdots f_{s}^{\nu_{s}}$.
Definition 10. (See Marshall, 2008.) The $\mathcal{A}$-radical of an ideal $I$ is defined as

$$
\sqrt[A]{I}:=\left\{p \in \mathbb{R}[x] \mid p^{2 k}+\sum_{\nu \in\{0,1\}^{s}} \sigma_{\nu} f^{\nu} \in I \text { for some } k \in \mathbb{N}, \sigma_{v} \in \sum \mathbb{R}[x]^{2}\right\}
$$

The ideal $I$ is called $\mathcal{A}$-radical if $I=\sqrt[\mathcal{A}]{I}$.

Theorem 6. (See Stengle, 1994, Semialgebraic Nullstellensatz.) Let I be an ideal in $\mathbb{R}[x]$ and $\mathcal{A}$ be defined by (20). Then $\sqrt[\mathcal{A}]{I}$ is an $\mathcal{A}$-radical ideal and $\sqrt[\mathcal{A}]{I}=I\left(V_{\mathbb{R}}(I) \cap \mathcal{A}\right)$.

To compute the $\mathcal{A}$-radical ideal $\sqrt[\mathcal{A}]{I}$, we consider the set

$$
\begin{equation*}
\mathcal{K}_{t, \mathcal{A}}:=\mathcal{K}_{t} \cap\left\{y \in \mathbb{R}^{\mathbb{N}_{2 t}^{n}}: M_{t-d_{f^{v}}}\left(f^{v} y\right) \succeq 0, \forall v \in\{0,1\}^{s}\right\} \tag{21}
\end{equation*}
$$

where $d_{f^{\nu}}=\left\lceil\operatorname{deg}\left(f^{\nu}\right) / 2\right\rceil$. Clearly, the set $\mathcal{K}_{t, \mathcal{A}}$ is a restriction of $\mathcal{K}_{t}$. The definition of the set $\mathcal{K}_{t, \mathcal{A}}$ is motivated by the polynomials in $\sqrt[\mathcal{A}]{I}$ and the Semialgebraic Nullstellensatz. The generic elements of $\mathcal{K}_{t, \mathcal{A}}$ are similarly defined to be the elements of the set

$$
\mathcal{K}_{t, \mathcal{A}}^{\text {gen }}:=\left\{y \in \mathcal{K}_{t, \mathcal{A}}: \operatorname{rank} M_{t}(y) \text { is maximum over } \mathcal{K}_{t, \mathcal{A}}\right\} .
$$

Lemma 4. (See Lasserre et al., 2008, Remark 4.9.) Let $\left\{g_{1}, \ldots, g_{k}\right\}$ be a set of generators for the ideal $\sqrt[A]{I}$. Then there exists $t_{0} \in \mathbb{N}$ such that $g_{1}, \ldots, g_{k} \in \operatorname{ker} M_{t}(y)$ for all $y \in \mathcal{K}_{t, \mathcal{A}}$ and $t \geq t_{0}$.

According to Lemma 4, it is easy to show that there exists $t_{0} \in \mathbb{N}$ such that $\left\langle\operatorname{ker} M_{t}(y)\right\rangle=\sqrt[\mathcal{A}]{I}$ for all $y \in \mathcal{K}_{t, \mathcal{A}}^{\text {gen }}$ and $t \geq t_{0}$. Hence, for $t$ large enough, the information about $\sqrt[\mathcal{A}]{I}$ will be contained in the projection of a generic element $y \in \mathcal{K}_{t, \mathcal{A}}$. Thus, propositions and theorems discussed above are true for generic elements $y$ in $\mathcal{K}_{t, \mathcal{A}}$.

The following theorem can be seen as a variant of Theorem 3 for the semialgebraic set $\mathcal{A}$. The proof uses exactly the same reasoning as in Theorem 4 and Theorem 5 after replacing $\mathcal{K}_{t}$ and $\sqrt[\mathbb{R}]{I}$ by $\mathcal{K}_{t, \mathcal{A}}$ and $\sqrt[\mathcal{A}]{I}$ respectively.

Theorem 7. Suppose the condition (7) holds for a generic element $y \in \mathcal{K}_{t, \mathcal{A}}$, and $t \geq 2 d$. Then a reduced basis of the null space of $M_{t-2}(y)$ is a weak Pommaret basis of $\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle$ under the monomial ordering $\prec_{\text {tdeg }}$ and

$$
I \subseteq\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle \subseteq I\left(V_{\mathbb{R}}(I) \cap \mathcal{A}\right)
$$

Remark 4. For computing a Pommaret basis of $\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle$, we add the defining polynomials $\left\{f_{1}, \ldots, f_{s}\right\}$ of the semialgebraic set $\mathcal{A}$ to the input of the above algorithm and additional constraints $M_{t-d_{f^{v}}}\left(f^{v} y\right) \succeq 0$ for all $v \in\{0,1\}^{s}$ to the semidefinite program (9).

## 4. Numerical examples

We present here the results obtained by applying Algorithm 1 to some examples taken from Rostalski (2009), Scott et al. (2009), Seiler (2002), Stetter (2004) and others. For a given tolerance $\tau$, we define the numerical rank of a matrix to be $k$, if its singular values satisfy $\sigma_{1} \geq \cdots \geq \sigma_{k}>\tau>\sigma_{k+1}$ or $\sigma_{k} / \sigma_{k+1}>10^{3}$. Spang implemented in SINGULAR (Decker et al., 2012) a symbolic algorithm realrad for computing the real radical of an arbitrary ideal over transcendental extension of the rational numbers (Silke, 2007b). Since the algorithm realrad is based on Wu-Ritt's characteristic set method and Gröbner basis computation, it has double-exponential complexity. Our algorithm is based on semidefinite programming and numerical linear algebra, it has polynomial complexity. However, the results we computed may contain numerical errors. Using realrad, we can verify that Examples 2, 3, 5 are real radical ideals, i.e. $I=\sqrt[\mathbb{R}]{I}$ and Examples 4, 6 are not real radical ideals, i.e. $I \subset \sqrt[\mathbb{R}]{I}$.

Example 2. Consider the 2-dimensional ideal $I=\left\langle h_{1}, h_{2}, h_{3}\right\rangle$ taken from Stetter (2004, p. 397, Eq. (9.60)) where

$$
\begin{aligned}
& h_{1}=x_{1}^{2}+x_{1} x_{2}-x_{1} x_{3}-x_{1}-x_{2}+x_{3}, \\
& h_{2}=x_{1} x_{2}+x_{2}^{2}-x_{2} x_{3}-x_{1}-x_{2}+x_{3}, \\
& h_{3}=x_{1} x_{3}+x_{2} x_{3}-x_{3}^{2}-x_{1}-x_{2}+x_{3} .
\end{aligned}
$$

Table 1
The rank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :--- | :--- | :---: |
| $t=4$ | 16 | 11 | 7 |
| $t=5$ | 22 | 16 | 11 |
| $t=6$ | 29 | 22 | 16 |
| $t=7$ | 37 | 29 | 22 |

Table 2
The corank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :--- | :---: | :---: |
| $t=4$ | 19 | 9 | 3 |
| $t=5$ | 34 | 19 | 9 |
| $t=6$ | 55 | 34 | 19 |
| $t=7$ | 83 | 55 | 34 |

## Table 3

The $\alpha_{j}$ of a reduced basis of $\operatorname{ker} M_{t-2}(y)$.

| Order | $\alpha_{1}$ | $\alpha_{2}$ | $\alpha_{3}$ | $\sum_{j=1}^{3} j \alpha_{j}$ |
| :--- | ---: | :--- | :--- | :--- |
| $t=4$ | 1 | 1 | 1 | $1 \times 1+2 \times 1+3 \times 1=6$ |
| $t=5$ | 3 | 2 | 1 | $1 \times 3+2 \times 2+3 \times 1=10$ |
| $t=6$ | 6 | 3 | 1 | $1 \times 6+2 \times 3+3 \times 1=15$ |
| $t=7$ | 10 | 4 | 1 | $1 \times 10+2 \times 4+3 \times 1=21$ |

The rank and corank sequences for truncated moment matrices $M_{t-\ell}(y)$ are shown in Tables 1 and 2. We set $\tau=10^{-5}$ and $x_{1} \prec_{\text {tdeg }} x_{2} \prec_{\text {tdeg }} x_{3}$. For $t=4$, we have

$$
\sum_{j=1}^{3} j \alpha_{j}=6, \quad \text { and } \quad \operatorname{corank} M_{4-1}-\operatorname{corank} M_{4-2}=6
$$

Hence, the condition (7) is satisfied. The Pommaret basis computed by Algorithm 1 for $t=4$ is

$$
\begin{aligned}
& \left\{x_{1}+x_{2}-x_{3}-x_{1}^{2}-x_{1} x_{2}+x_{1} x_{3}, x_{1}+x_{2}-x_{3}-x_{1} x_{2}-x_{2}^{2}+x_{2} x_{3}\right. \\
& \left.\quad 3 x_{1}+3 x_{2}-3 x_{3}-x_{1}^{2}-2 x_{1} x_{2}-x_{2}^{2}+x_{3}^{2}\right\}
\end{aligned}
$$

From Table 3, we note that the condition (7) is also satisfied for $t=5,6,7$. For this example, using the function realrad, we can show that $I=\left\langle\operatorname{ker} M_{4-2}(y)\right\rangle=\sqrt[\mathbb{R}]{I}$, and a reduced basis of $\operatorname{ker} M_{4-2}(y)$ is a Pommaret basis of $\sqrt[\mathbb{R}]{I}$. Hence, the condition (7) can be satisfied by arbitrary $t \geq 4$.

Example 3. Consider the polynomial system $P=\left\{h_{1}, h_{2}\right\}$ in Scott et al. (2009, p. 20, Ex. 1.4.6) where

$$
\begin{aligned}
& h_{1}=x_{1}^{2}-x_{2} \\
& h_{2}=x_{1} x_{2}-x_{3}
\end{aligned}
$$

For the term order $x_{3} \prec_{\text {tdeg }} x_{1} \prec_{\text {tdeg }} x_{2}$, we have $\operatorname{cls}\left(x_{1}\right)=2, \operatorname{cls}\left(x_{2}\right)=3, \operatorname{cls}\left(x_{3}\right)=1$. Let $\tau=10^{-8}$, the rank and corank sequences for truncated moment matrices $M_{t-\ell}(y)$ are shown in Tables 4 and 5 .

For $t=4$, from Tables 5 and 6 we have

$$
\sum_{j=1}^{3} j \alpha_{j}=7, \quad \text { and } \quad \text { corank } M_{4-1}-\operatorname{corank} M_{4-2}=7
$$

Hence, the condition (7) is satisfied. The Pommaret basis computed by Algorithm 1 for $t=4$ is

$$
\left\{x_{1}^{2}-x_{2}, x_{1} x_{2}-x_{3}, x_{2}^{2}-x_{1} x_{3}\right\}
$$

which is also the basis of $\sqrt[\mathbb{R}]{I}$ computed by the function realrad. Moreover, since $x_{2}^{2}-x_{1} x_{3}=$ $x_{1}\left(x_{1} x_{2}-x_{3}\right)-x_{2}\left(x_{1}^{2}-x_{2}\right)$, we have $I=\left\langle\operatorname{ker} M_{4-2}(y)\right\rangle=\sqrt[\mathbb{R}]{I}$.

Table 4
The rank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :--- | :---: | :---: |
| $t=3$ | 12 | 7 | 4 |
| $t=4$ | 16 | 10 | 7 |
| $t=5$ | 20 | 13 | 10 |

Table 5
The corank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :---: | :---: | :---: |
| $t=3$ | 8 | 3 | 0 |
| $t=4$ | 19 | 10 | 3 |
| $t=5$ | 36 | 22 | 10 |

## Table 6

The $\alpha_{j}$ of a reduced basis of $\operatorname{ker} M_{t-2}(y)$.

| Order | $\alpha_{1}$ | $\alpha_{2}$ | $\alpha_{3}$ | $\sum_{j=1}^{3} j \alpha_{j}$ |
| :--- | :--- | :--- | :--- | :--- |
| $t=3$ | 0 | 0 | 0 | $1 \times 0+2 \times 0+3 \times 0=0$ |
| $t=4$ | 0 | 2 | 1 | $1 \times 0+2 \times 2+3 \times 1=7$ |
| $t=5$ | 3 | 3 | 1 | $1 \times 3+2 \times 3+3 \times 1=12$ |

Table 7
The rank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :---: | :---: | :--- |
| $t=3$ | 7 | 5 | 3 |
| $t=4$ | 9 | 7 | 5 |
| $t=5$ | 11 | 9 | 7 |
| $t=6$ | 13 | 11 | 9 |

Table 8
The corank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :--- | :---: | :---: |
| $t=3$ | 13 | 5 | 1 |
| $t=4$ | 26 | 13 | 5 |
| $t=5$ | 45 | 26 | 13 |
| $t=6$ | 71 | 45 | 26 |

## Table 9

The $\alpha_{j}$ of a reduced basis of $\operatorname{ker} M_{t-2}(y)$.

| Order | $\alpha_{1}$ | $\alpha_{2}$ | $\alpha_{3}$ | $\sum_{j=1}^{3} j \alpha_{j}$ |
| :--- | :--- | :--- | :--- | :--- |
| $t=3$ | 0 | 0 | 1 | $1 \times 0+2 \times 0+3 \times 1=3$ |
| $t=4$ | 1 | 2 | 1 | $1 \times 1+2 \times 2+3 \times 1=8$ |
| $t=5$ | 4 | 3 | 1 | $1 \times 4+2 \times 3+3 \times 1=13$ |
| $t=6$ | 8 | 4 | 1 | $1 \times 8+2 \times 4+3 \times 1=19$ |

Example 4. Consider the ideal $I=\left\langle h_{1}, h_{2}\right\rangle$ in Rostalski (2009, p. 123, Ex. 7.41) with

$$
\begin{aligned}
& h_{1}=x_{1}^{2}+x_{2}^{2}+x_{3}^{2}-2 \\
& h_{2}=x_{1}^{2}+x_{2}^{2}-x_{3}
\end{aligned}
$$

Applying the function realrad, we obtain generators

$$
\begin{equation*}
\left\{x_{3}-1, x_{1}^{2}+x_{2}^{2}-1\right\} \tag{22}
\end{equation*}
$$

of the real radical ideal $\sqrt[\mathbb{R}]{I}$. Since $x_{3}-1$ is not in the ideal $I$, we can deduce that $I$ is strictly contained in $\sqrt[\mathbb{R}]{I}$, i.e. $I \subset \sqrt[\mathbb{R}]{I}$. Let $\tau=10^{-8}$ and $x_{1} \prec_{\text {tdeg }} x_{2} \prec_{\text {tdeg }} x_{3}$, the rank and corank sequences for truncated moment matrices $M_{t-\ell}(y)$ are shown in Tables 7 and 8.

For $t=4$, from Tables 8 and 9 , we have

$$
\sum_{j=1}^{3} j \alpha_{j}=8, \text { and corank } M_{4-1}-\operatorname{corank} M_{4-2}=8
$$

Hence, the condition (7) is satisfied. The Pommaret basis computed by Algorithm 1 for $t=4$ is

$$
\begin{equation*}
\left\{-1+x_{3},-1+x_{1}^{2}+x_{2}^{2}\right\} \tag{23}
\end{equation*}
$$

which is the same as the basis (22) of $\sqrt[\mathbb{R}]{I}$ computed by realrad. Therefore, we have $\left\langle\operatorname{ker} M_{4-2}(y)\right\rangle=$ $\sqrt[\mathbb{R}]{I}$, and the reduced basis (23) of $\operatorname{ker} M_{4-2}(y)$ is a Pommaret basis of $\sqrt[\mathbb{R}]{I}$. Hence, the condition (7) can be satisfied by arbitrary $t \geq 4$.

Table 10
The rank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :--- | :--- | :---: |
| $t=4$ | 13 | 10 | 7 |
| $t=5$ | 16 | 13 | 10 |
| $t=6$ | 19 | 16 | 13 |
| $t=7$ | 22 | 19 | 16 |

Table 11
The corank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :--- | :--- | :---: |
| $t=4$ | 22 | 10 | 3 |
| $t=5$ | 40 | 22 | 10 |
| $t=6$ | 65 | 40 | 22 |
| $t=7$ | 98 | 65 | 40 |

Table 12
The $\alpha_{j}$ of a reduced basis of $\operatorname{ker} M_{t-2}(y)$.

| Order | $\alpha_{1}$ | $\alpha_{2}$ | $\alpha_{3}$ | $\sum_{j=1}^{3} j \alpha_{j}$ |
| :--- | ---: | :--- | :--- | :--- |
| $t=4$ | 1 | 1 | 1 | $1 \times 1+2 \times 1+3 \times 1=6$ |
| $t=5$ | 4 | 2 | 1 | $1 \times 4+2 \times 2+3 \times 1=11$ |
| $t=6$ | 8 | 3 | 1 | $1 \times 8+2 \times 3+3 \times 1=17$ |
| $t=7$ | 13 | 4 | 1 | $1 \times 13+2 \times 4+3 \times 1=24$ |

Example 5. Consider the ideal $I=\left\langle h_{1}, h_{2}, h_{3}\right\rangle$ in Seiler (2002, p. 61, Ex. 2.4.12) where

$$
\begin{aligned}
& h_{1}=x_{3}^{2}+x_{2} x_{3}-x_{1}^{2}, \\
& h_{2}=x_{1} x_{3}+x_{1} x_{2}-x_{3}, \\
& h_{3}=x_{2} x_{3}+x_{2}^{2}+x_{1}^{2}-x_{1} .
\end{aligned}
$$

Let $\tau=10^{-7}$ and the term order be $x_{1} \prec_{\text {tdeg }} x_{2} \prec_{\text {tdeg }} x_{3}$. The rank and corank sequences for the truncated moment matrices $M_{t-\ell}(y)$ are shown in Tables 10 and 11.

From Tables 11 and 12, we know that the condition (7) cannot be satisfied for $t$ from 4 to 7 . Actually, Seiler showed in Seiler (2002) that the coordinates ( $x_{1}, x_{2}, x_{3}$ ) are not $\delta$-regular for the ideal $I$. However, if we perform the linear transformation suggested in Seiler (2002), $\tilde{x}_{1}=x_{3}, \tilde{x}_{2}=$ $x_{2}+x_{3}, \tilde{x}_{3}=x_{1}$, after an auto-reduction, we obtain the polynomial system $\tilde{P}=\left\{\tilde{x}_{1} \tilde{x}_{2}-\tilde{x}_{3}^{2}, \tilde{x}_{2} \tilde{x}_{3}-\right.$ $\left.\tilde{x}_{1}, \tilde{x}_{2}^{2}-\tilde{x}_{3}\right\}$.

Let $\tilde{I}$ be the ideal generated by $\tilde{P}$. The generators of $\sqrt[\mathbb{R}]{\tilde{I}}$ computed by the function realrad are

$$
\begin{equation*}
\left\{\tilde{x}_{1} \tilde{x}_{2}-\tilde{x}_{3}^{2}, \tilde{x}_{2} \tilde{x}_{3}-\tilde{x}_{1}, \tilde{x}_{2}^{2}-\tilde{x}_{3}, \tilde{x}_{3}^{3}-\tilde{x}_{1}^{2}\right\} . \tag{24}
\end{equation*}
$$

Since $\tilde{x}_{3}^{3}-\tilde{x}_{1}^{2}=-\tilde{x}_{3}\left(\tilde{x}_{1} \tilde{x}_{2}-\tilde{x}_{3}^{2}\right)+\tilde{x}_{1}\left(\tilde{x}_{2} \tilde{x}_{3}-\tilde{x}_{1}\right)$, we can deduce that $\tilde{I}=\sqrt[R]{I}$.
Choosing an ordering $\tilde{x}_{1}<_{\text {tdeg }} \tilde{x}_{2}<_{\text {tdeg }} \tilde{x}_{3}$ and $\tau=10^{-8}$, the rank and corank sequences for the truncated moment matrices $M_{t-\ell}(y)$ are shown in Tables 13 and 14.

For $t=4$, from Tables 14 and 15, we have

$$
\sum_{j=1}^{3} j \alpha_{j}=7, \quad \text { and } \quad \text { corank } M_{4-1}-\operatorname{corank} M_{4-2}=7
$$

Hence, the condition (7) is satisfied. The Pommaret basis computed by Algorithm 1 for $t=4$ is

$$
\begin{equation*}
\left\{\tilde{x}_{1} \tilde{x}_{2}-\tilde{x}_{3}^{2}, \tilde{x}_{2} \tilde{x}_{3}-\tilde{x}_{1}, \tilde{x}_{2}^{2}-\tilde{x}_{3}\right\} . \tag{25}
\end{equation*}
$$

By (24), we know that (25) is also a Pommaret basis of $\sqrt[\mathbb{R}]{\tilde{I} \text {. }}$

Table 13
The rank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :--- | :--- | :---: |
| $t=4$ | 13 | 10 | 7 |
| $t=5$ | 16 | 13 | 10 |
| $t=6$ | 19 | 16 | 13 |

Table 14
The corank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :--- | :--- | :---: |
| $t=4$ | 22 | 10 | 3 |
| $t=5$ | 40 | 22 | 10 |
| $t=6$ | 65 | 40 | 22 |

## Table 15

The $\alpha_{j}$ of a reduced basis of $\operatorname{ker} M_{t-2}(y)$.

| Order | $\alpha_{1}$ | $\alpha_{2}$ | $\alpha_{3}$ | $\sum_{j=1}^{3} j \alpha_{j}$ |
| :--- | :--- | :--- | :--- | :--- |
| $t=4$ | 0 | 2 | 1 | $1 \times 0+2 \times 2+3 \times 1=7$ |
| $t=5$ | 3 | 3 | 1 | $1 \times 3+2 \times 3+3 \times 1=12$ |
| $t=6$ | 7 | 4 | 1 | $1 \times 7+2 \times 4+3 \times 1=18$ |

Table 16
The rank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :--- | :--- | :--- |
| $t=7$ | 15 | 13 | 11 |
| $t=8$ | 17 | 15 | 13 |
| $t=9$ | 19 | 17 | 15 |

Table 17
The corank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :--- | :--- | :--- |
| $t=7$ | 21 | 15 | 10 |
| $t=8$ | 28 | 21 | 15 |
| $t=9$ | 36 | 28 | 21 |

Table 18
The $\alpha_{j}$ of a reduced basis of $\operatorname{ker} M_{t-2}(y)$.

| Order | $\alpha_{1}$ | $\alpha_{2}$ | $\sum_{j=1}^{2} j \alpha_{j}$ |
| :--- | :--- | :--- | :--- |
| $t=7$ | 3 | 1 | $1 \times 3+2 \times 1=5$ |
| $t=8$ | 4 | 1 | $1 \times 4+2 \times 1=6$ |
| $t=9$ | 5 | 1 | $1 \times 5+2 \times 1=7$ |

Example 6. Consider the ideal $I=\left\langle h_{1}, h_{2}\right\rangle$, where

$$
\begin{aligned}
& h_{1}=\left(x_{1}-x_{2}\right)\left(x_{1}+x_{2}\right)^{2}\left(x_{1}+x_{2}^{2}+x_{2}\right), \\
& h_{2}=\left(x_{1}-x_{2}\right)\left(x_{1}+x_{2}\right)^{2}\left(x_{1}^{2}+x_{2}^{2}\right) .
\end{aligned}
$$

Applying the function realrad, we obtain a generator set

$$
\begin{equation*}
\left\{x_{1}^{2}-x_{2}^{2}\right\} \tag{26}
\end{equation*}
$$

of $\sqrt[\mathbb{R}]{I}$. Since $x_{1}^{2}-x_{2}^{2}$ is not in the ideal $I$, we can deduce that $I$ is strictly contained in $\sqrt[\mathbb{R}]{I}$, i.e. $I \subset \sqrt[\mathbb{R}]{I}$. Let $\tau=10^{-4}$ and $x_{1} \prec_{\text {tdeg }} x_{2}$, the rank and corank sequences for the truncated moment matrices $M_{t-\ell}(y)$ are shown in Tables 16 and 17.

For $t=7$, from Tables 17 and 18, we have

$$
\sum_{j=1}^{2} j \alpha_{j}=5, \quad \text { and } \quad \operatorname{corank} M_{7-1}-\operatorname{corank} M_{7-2}=5
$$

Hence, the condition (7) is satisfied. The Pommaret basis computed by Algorithm 1 for $t=7$ is

$$
\begin{equation*}
\left\{-x_{1}^{2}+x_{2}^{2}\right\} . \tag{27}
\end{equation*}
$$

By (26) and (27), we have shown that $\left\langle\operatorname{ker} M_{7-2}(y)\right\rangle=\sqrt[\mathbb{R}]{I}$, and the reduced basis (27) is a Pommaret basis of $\sqrt[\mathbb{R}]{I}$.

Table 19
The rank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :---: | :--- | :--- |
| $t=6$ | 8 | 6 | 5 |
| $t=7$ | 9 | 7 | 6 |
| $t=8$ | 10 | 8 | 7 |

Table 20
The corank of $M_{t-\ell}(y)$.

| Order | $\ell=0$ | $\ell=1$ | $\ell=2$ |
| :--- | :--- | :--- | :--- |
| $t=6$ | 20 | 15 | 10 |
| $t=7$ | 27 | 21 | 15 |
| $t=8$ | 35 | 28 | 21 |

## Table 21

The $\alpha_{j}$ of a reduced basis of $\operatorname{ker} M_{t-2}(y)$.

| Order | $\alpha_{1}$ | $\alpha_{2}$ | $\sum_{j=1}^{2} j \alpha_{j}$ |
| :--- | :--- | :--- | :--- |
| $t=6$ | 3 | 1 | $1 \times 3+2 \times 1=5$ |
| $t=7$ | 4 | 1 | $1 \times 4+2 \times 1=6$ |
| $t=8$ | 5 | 1 | $1 \times 5+2 \times 1=7$ |

It should be noticed that for this example, if we set tolerance $\tau<10^{-4}$, the rank and corank sequences for the truncated moment matrices $M_{t-\ell}(y)$ will be completely different from those shown in Tables 16 and 17 , and we cannot get $\left\{-x_{1}^{2}+x_{2}^{2}\right\}$ as a Pommaret basis of $\sqrt[\mathbb{R}]{I}$.

Example 7. We compute $I\left(V_{\mathbb{R}}(I) \cap \mathcal{A}\right)$ for $I=\left\langle h_{1}, h_{2}\right\rangle$,

$$
\begin{aligned}
& h_{1}=\left(x_{1}-x_{2}\right)\left(x_{1}+x_{2}\right)\left(x_{1}+x_{2}^{2}+x_{2}\right), \\
& h_{2}=\left(x_{1}-x_{2}\right)\left(x_{1}+x_{2}\right)\left(x_{1}^{2}+x_{2}^{2}\right),
\end{aligned}
$$

and

$$
\mathcal{A}=\left\{\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2} \mid x_{1} \geq 1, x_{2} \geq 1\right\} .
$$

Let us set $\tau=10^{-8}$ and $x_{1} \prec_{\text {tdeg }} x_{2}$, the rank and corank sequences for the truncated moment matrices $M_{t-\ell}(y)$ with $y \in \mathcal{K}_{t, \mathcal{A}}$ are shown in Tables 19 and 20.

For $t=6$, from Tables 20 and 21, we have

$$
\sum_{j=1}^{2} j \alpha_{j}=5, \quad \text { and } \quad \operatorname{corank} M_{6-1}-\operatorname{corank} M_{6-2}=5
$$

Hence, the condition (7) is satisfied. The Pommaret basis we obtain by Algorithm 1 for $t=6$ is

$$
\left\{-x_{1}+x_{2}\right\}
$$

for $I\left(V_{\mathbb{R}}(I) \cap \mathcal{A}\right)$.

## 5. Concluding remarks

In this paper we present a semidefinite characterization for computing a Pommaret basis of an ideal $J$, where $J$ is generated by polynomials in the kernel of a truncated moment matrix and satisfies $I \subseteq J \subseteq I\left(V_{\mathbb{R}}(I)\right)$. Our approach is stimulated by the previous work in Lasserre et al. (2008, 2009a), Laurent and Rostalski (2010), Reid and Zhi (2009), Rostalski (2009), Scott (2006), Scott et al. (2009), Seiler (2002). By combining the geometric involutive theory with the results on positive semidefinite moment matrices, we introduce a new stopping condition (7) for the semidefinite program (9) and prove the finite termination of the algorithm in a $\delta$-regular coordinate system. Although we still could not provide a certificate to check whether $J=\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle=I\left(V_{\mathbb{R}}(I)\right)$, it is interesting to show some related work below which might lead to a solution to this problem in future.

Remark 5. In zero-dimensional case, if the flat extension condition is satisfied at $s \leq t$, i.e. $\operatorname{rank} M_{s}(y)=\operatorname{rank} M_{s-1}(y)$ for $y \in \mathcal{K}_{t}^{\text {gen }}$, then $\left\langle\operatorname{ker} M_{s}(y)\right\rangle=I\left(V_{\mathbb{R}}(I)\right)$ and $\operatorname{corank} M_{s}(y)-$
corank $M_{s-1}(y)=\binom{n+s-1}{s}$, which means that monomials of degree $s$ all appear in the reduced basis of $\operatorname{ker} M_{s}(y)$. Hence we have $\sum_{j=1}^{n} j \alpha_{j}=\binom{n+s}{s+1}$ for $\operatorname{ker} M_{s}(y)$.

If $s<t-1$, by the ideal-like property given in Proposition 1(i), we can show that $\operatorname{rank} M_{s}(y)=$ $\operatorname{rank} M_{s+1}(y)$, i.e. corank $M_{s+1}(y)-\operatorname{corank} M_{s}(y)=\binom{n+s}{s+1}$. Therefore, our condition (7) is satisfied for $\operatorname{ker} M_{s}(y)$ and a reduced basis of $\operatorname{ker} M_{s}(y)$ is a weak Pommaret basis for $J=\left\langle\operatorname{ker} M_{s}(y)\right\rangle=I\left(V_{\mathbb{R}}(I)\right)$ under the monomial ordering $\prec_{\text {tdeg }}$.

If $s=t-1$, using Proposition 1(i) and Proposition 2(ii), it is straightforward to show that the flat extension condition is also satisfied at $s$ for $y^{\prime} \in \mathcal{K}_{t+1}^{\text {gen }}$, i.e. $\operatorname{rank} M_{s}\left(y^{\prime}\right)=\operatorname{rank} M_{s-1}\left(y^{\prime}\right)$. Hence, $\operatorname{rank} M_{s}\left(y^{\prime}\right)=\operatorname{rank} M_{s+1}\left(y^{\prime}\right)$, and the condition (7) will be satisfied at $M_{s}\left(y^{\prime}\right)$ and $J=\left\langle\operatorname{ker} M_{s}\left(y^{\prime}\right)\right\rangle=$ $I\left(V_{\mathbb{R}}(I)\right)$. If $s=t$, similarly, we can show that the condition (7) will be satisfied at $M_{s}\left(y^{\prime \prime}\right)$ for $y^{\prime \prime} \in$ $\mathcal{K}_{t+2}^{\text {gen }}$ and $J=\left\langle\operatorname{ker} M_{s}\left(y^{\prime \prime}\right)\right\rangle=I\left(V_{\mathbb{R}}(I)\right)$.

Remark 6. From the tables in Section 4, we can check that the condition (7) can be satisfied by higher order moment matrices once it is satisfied at order $t$. Moreover, we can also check that the condition

$$
\begin{equation*}
\operatorname{rank} M_{t^{\prime}-\ell}\left(y_{1}\right)=\operatorname{rank} M_{\left(t^{\prime}+1\right)-(\ell+1)}\left(y_{2}\right), \quad \text { for } t^{\prime} \geq t, \quad \ell=1,2 \tag{28}
\end{equation*}
$$

is satisfied for $y_{1} \in \mathcal{K}_{t^{\prime}}^{\mathrm{gen}}$ and $y_{2} \in \mathcal{K}_{t^{\prime}+1}^{\mathrm{gen}}$. However, in general we cannot guarantee this property. It is clear that if both (7) and (28) hold for all higher order moment matrices, then for all $k \geq 0$ and all generic $y \in \mathcal{K}_{t+k}^{\text {gen }}$, we have

$$
\begin{equation*}
\operatorname{rank} M_{t+k-\ell}(y)=H P_{\sqrt[P]{I} I}^{\mathrm{aff}}(t+k-\ell) \tag{29}
\end{equation*}
$$

where $H P_{\sqrt[1]{\mathbb{R}} / \sqrt{I}}^{\text {al }}(t+k-\ell)$ is the affine Hilbert polynomial of $\sqrt[\mathbb{R}]{I}$ which counts the dimension of polynomials of $\mathbb{K}[x]_{\leq t+k-\ell}$ not lying in $\sqrt[\mathbb{R}]{I_{\leq t+k-\ell}}$ (Ma, 2012, Theorem 5.20). Therefore, a reduced basis of $\operatorname{ker} M_{t-\ell}(y)$ is a weak Pommaret basis for $J=\left\langle\operatorname{ker} M_{t-\ell}(y)\right\rangle=I\left(V_{\mathbb{R}}(I)\right)$ under the monomial ordering $<_{\text {tdeg }}$ (Ma, 2012, Theorem 5.21).

Remark 7. Let $I=\left\langle h_{1}, \ldots, h_{m}\right\rangle$, and $\operatorname{dim}(I)=s>0$. For each polynomial $f \in \sqrt[\mathbb{R}]{I}$, there exist $t, r \in \mathbb{N}$ and polynomials $q_{1}, \ldots, q_{r}, p_{1}, \ldots, p_{m} \in \mathbb{R}[x]$ such that

$$
\begin{equation*}
f^{2 \tau}+\sum_{i=1}^{r} q_{i}^{2}=\sum_{i=1}^{m} p_{i} h_{i} \tag{30}
\end{equation*}
$$

Some interesting bounds $D(n, \operatorname{deg}(f), s)$ for $\operatorname{deg}\left(p_{i} h_{i}\right), i=1, \ldots, m$ have been given in Henri et al. (2014), Schmid (1998, 2000). Suppose we know the degree upper bound $k_{1}$ for the generators of $\sqrt[\mathbb{R}]{I}$, then we have $\operatorname{deg}\left(p_{i} h_{i}\right) \leq k_{2}=D\left(n, k_{1}, s\right)$. By (30) and Proposition 1(ii), we know that all generators of $\sqrt[\mathbb{R}]{I}$ will be included in $\operatorname{ker} M_{k_{2}}(y)$. Therefore, if the condition (7) is satisfied at $t-2>k_{2}$ then a reduced basis of $\operatorname{ker} M_{t-2}(y)$ is a weak Pommaret basis for $J=\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle=I\left(V_{\mathbb{R}}(I)\right)$ under the monomial ordering $\prec_{\text {tdeg }}$.

In general, it is difficult to estimate the degree upper bound $k_{1}$ for the generators in $\sqrt[\mathbb{R}]{I}$. We know that the Castelnuovo-Mumford regularity of a homogenous ideal is $q$ if and only if the ideal has in some suitably chosen coordinates a Pommaret basis of degree $q$ for the graded reverse lexicographic order (Seiler, 2010, Theorem 5.5.15). Therefore, the Pommaret basis we computed for $J=\left\langle\operatorname{ker} M_{t-2}(y)\right\rangle$ can be used to bound the degree of the generators of $I\left(V_{\mathbb{R}}(I)\right)$ in some cases (Ravi, 1990).

Finally, we wish to mention that results computed by semidefinite programming and numerical linear algebra are approximate. Therefore, our condition (7) can only be checked with respect to a given tolerance. For improperly chosen tolerance, we might not be able to give a meaningful answer.

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