

$$1. V = \langle \vec{e}_1, \dots, \vec{e}_4 \rangle, \vec{e}_1 = \vec{e}_1, \vec{e}_2 = -\vec{e}_1, \vec{e}_3 = 2\vec{e}_1 + 3\vec{e}_4, \vec{e}_4 = 4\vec{e}_3 + \vec{e}_4$$

(ii) $\text{char}(F) = 0$. 证明 $\vec{e}_1, \dots, \vec{e}_4$ 构成基. 并求矩阵 $A, B \in M_4(F)$ 使

$$(\vec{e}_1, \dots, \vec{e}_4) = (\vec{e}_1, \dots, \vec{e}_4) A, \quad (\vec{e}_1, \dots, \vec{e}_4) = (\vec{e}_1, \dots, \vec{e}_4) B.$$

(iii) $\text{char}(F) = ?$ $\vec{e}_1, \dots, \vec{e}_4$ 不是基底.

解 (i). $(\vec{e}_1, \dots, \vec{e}_4) = (\vec{e}_1, \dots, \vec{e}_4) \begin{pmatrix} 1 & -1 & 2 & 3 \\ & 1 & 4 & 1 \end{pmatrix}^A$

$$|A| = +10 \quad \therefore \text{char}(F) = 0$$

$$\therefore |A| \neq 0$$

$\because \text{rank } A = 4 \quad \therefore \vec{e}_1, \dots, \vec{e}_4$ 构成基.

$$B = A^{-1} = \begin{pmatrix} 1 & -1 & -\frac{1}{10} & \frac{2}{10} \\ & 1 & \frac{3}{10} & -\frac{1}{10} \end{pmatrix}$$

(ii) $\because |A| = 10 \quad \therefore \text{char}(F) = 2 \text{ 或 } 5 \text{ 时 } |A| = 0 \Rightarrow A \text{ 不满秩} \Rightarrow \text{不构成基}.$

$$2. q(x_1, x_2, x_3) = -3x_3^2 + 4x_1x_2$$

$$(i) A = \begin{pmatrix} 0 & 2 & 0 \\ 2 & 0 & 0 \\ 0 & 0 & -3 \end{pmatrix}$$

$$(ii) \text{ 行列式法: } (A \mid E) = \begin{pmatrix} 0 & 2 & 0 & 1 & 0 & 0 \\ 2 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & -3 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{(2)+(1)} \xrightarrow{(ii)+(i)} \begin{pmatrix} 4 & 2 & 0 & 1 & 0 & 0 \\ 2 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & -3 & 0 & 0 & 1 \end{pmatrix}$$

$$\xrightarrow{-\frac{1}{2}(1)+(2)} \xrightarrow{-\frac{1}{2}(i)+(ii)} \begin{pmatrix} 4 & 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & -3 & 0 & 0 & 1 \end{pmatrix} \Leftrightarrow P = \begin{pmatrix} 1 & -\frac{1}{2} & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{且 } P^TAP = \begin{pmatrix} 4 & & & \\ & 1 & & \\ & & 1 & \\ & & & -3 \end{pmatrix}$$

$$\text{圆2方法} \quad q = -3x_3^2 + 4x_1x_2 \quad \Leftrightarrow x_1 = y_1 + y_2, \quad x_2 = y_1 - y_2, \quad x_3 = y_3$$

$$= -3y_3^2 + 4y_1^2 - 4y_2^2 \quad \vec{x} = \begin{pmatrix} 1 & 1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \vec{y} \quad \text{且 } P = \begin{pmatrix} 1 & 1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} P^TAP = \begin{pmatrix} 4 & & & \\ & 1 & & \\ & & 1 & \\ & & & -3 \end{pmatrix}$$

(iii) 正惯性指数 1 负惯性指数 2.

$$3. A = \begin{pmatrix} 1 & 4 & \cdots & 4 \\ 4 & 1 & \cdots & 4 \\ \vdots & \vdots & \ddots & \vdots \\ 4 & 4 & \cdots & 1 \end{pmatrix} \in M_n(\mathbb{R})$$

$$(i) \Delta_k = \begin{vmatrix} 1 & 4 & \cdots & 4 \\ \vdots & \ddots & \vdots & \vdots \\ 4 & 4 & \cdots & 1 \end{vmatrix} = \begin{vmatrix} 4(k-1)+1 & 4 & \cdots & 4 \\ \vdots & 1 & \ddots & \vdots \\ 4(k-1)+1 & 4 & \cdots & 1 \end{vmatrix} = 4(k-1)+1 \begin{vmatrix} 1 & 4 & \cdots & 4 \\ \vdots & \ddots & \vdots & \vdots \\ 1 & 4 & \cdots & 1 \end{vmatrix}$$

$$= (4(k-1)+1) \cdot \begin{vmatrix} 1 & 3 & \cdots & 3 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 0 & \cdots & -3 \end{vmatrix} = (4k-3)(-3)^{k-1}$$

$$\frac{\Delta_{k+1}}{\Delta_k} = \frac{4k+1}{4k-3} \cdot (-3) < 0 \quad (\forall k \geq 1) \quad \Delta_1 = 1 > 0 \quad \Delta_0 = 1 > 0$$

由 Jacobi 方法 $A \sim_C \begin{pmatrix} \frac{\Delta_0}{\Delta_0} & & & \\ & \frac{\Delta_1}{\Delta_0} & & \\ & & \ddots & \\ & & & \frac{\Delta_{2n-1}}{\Delta_{2n-1}} \end{pmatrix}$ ∴ 等价为 $(1, 2n-1)$

(ii) 当 $n=1$ 时 $A \sim$ 等价为 $(1, 1) \Leftrightarrow (1, 1)$ 合同

当 $n>1$ 时 $A \sim$ 等价为 $(1, 2n-1) \neq (n, n) \therefore A \not\sim (E_n, E_n)$ 合同

(i) 中是半性算子

(ii) 考虑 $\text{rank } \phi$ (iii) $\text{ker } \phi \leq \text{im } \phi$ 中是否是直和.

$$4. \phi : M_n(\mathbb{C}) \rightarrow M_n(\mathbb{C})$$

$$A \mapsto A - A^t$$

$$\text{PF: (i)} \forall \alpha, \beta \in \mathbb{C}, A, B \in M_n(\mathbb{C}) \quad \phi(\alpha A + \beta B) = (\alpha A + \beta B) - (\alpha A + \beta B)^t$$

$$= \alpha(A - A^t) + \beta(B - B^t)$$

$$= \alpha\phi(A) + \beta\phi(B) \Rightarrow \text{线性}$$

$$\text{(ii) } \text{rank } \phi = \dim(\text{im } \phi), \forall A \in M_n(\mathbb{C}) \quad \phi(A) \text{ 是斜对称矩阵} \quad (A - A^t)^t = A^t - A = -(A - A^t)$$

$$\forall \text{斜对称矩阵 } B \quad (B^t = -B) \quad \exists A = \frac{B}{2} \text{ s.t. } \phi(A) = \frac{B}{2} - (\frac{B}{2})^t = \frac{B}{2} + \frac{B}{2} = B$$

$$\therefore \text{im } \phi = A M_n(\mathbb{C}) \quad (\text{斜对称矩阵空间}) \quad \therefore \dim(\text{im } \phi) = \frac{n(n-1)}{2} \therefore \text{rank } \phi = \frac{n(n-1)}{2}$$

$$\text{(iii). } \forall B \in \text{ker } \phi \cap \text{im } \phi \quad \exists A \in M_n(\mathbb{C}) \text{ s.t. } B = \phi(A) = A - A^t \Rightarrow B \text{ 斜对称.}$$

$$\text{且 } \phi(B) = (A - A^t) - (A - A^t)^t = A - A^t - A^t - B^t = 0 \Rightarrow B = B^t \Rightarrow B \text{ 对称.}$$

$$\therefore B = 0 \Rightarrow \text{矛盾.}$$

$$3. (i) \dim(U_1 + U_2 + U_3) \leq \dim(U_1) + \dim(U_2) + \dim(U_3)$$

$$\begin{aligned} \dim(U_1 + U_2 + U_3) &= \dim(U_1 + U_2) + \dim U_3 - \dim(U_1 + U_2) \cap U_3 \\ &= \dim U_1 + \dim U_2 - \dim(U_1 \cap U_2) + \dim U_3 - \dim(U_1 \cap U_2) \cap U_3 \\ &= \dim U_1 + \dim U_2 + \dim U_3 - \dim(U_1 \cap U_2) - \dim(U_1 + U_2) \cap U_3 \\ &\leq \dim U_1 + \dim U_2 + \dim U_3 \end{aligned}$$

$$(ii) \dim(U_1 + U_2) \cap U_3) + \dim(U_1 \cap U_2) = \dim((U_1 + U_2) \cap U_3) + \dim(U_1 \cap U_2)$$

$$\dim(U_1 + U_2 + U_3) = \dim(U_1 + U_2 + U_3) = \dim U_1 + \dim U_2 + \dim U_3 - \dim(U_1 \cap U_2) - \dim(U_1 + U_2) \cap U_3$$

$$\therefore \dim(U_1 \cap U_3) + \dim(U_1 + U_2) \cap U_2) = \dim U_1 + \dim U_2 + \dim U_3 - \dim(U_1 + U_2 + U_3)$$

$$\dim(U_1 \cap U_2) + \dim(U_1 + U_2) \cap U_3) \quad \square$$

$$6. A \in \mathcal{L}(V) \xrightarrow{\text{def}} A^2 = -A \quad \text{由 (i)} :$$

$$(i) \ker A + \text{im } A = V$$

$$(ii) \dim(\ker(A + \varepsilon)) = \text{rank } A$$

$$\text{If (iii) } f(t) \in (\mathbb{Q}[t]) \xrightarrow{\text{def}} f(t) = t^2 + t = (t+1)t$$

$$\therefore \gcd(t+1, t) = 1 \quad \text{且} \quad f(A) = 0$$

$$\therefore \ker(A + \varepsilon) \oplus \ker A = V$$

$$\begin{aligned} \Rightarrow \dim(\ker(A + \varepsilon)) &= \dim V - \dim(\ker A) \\ &= \dim(\text{im } A) \\ &= \text{rank } A. \end{aligned}$$

$$(i) \because A^2 = -A \quad \therefore \text{rank } A^2 = \text{rank } (-A) = \text{rank } A$$

$$\text{由核像分解} \quad \ker A \oplus \text{im } A = V \Rightarrow \ker A + \text{im } A = V \quad \square$$

7. $A, B \in SM_n(\mathbb{R})$ 正定

(i) $A^2 \leq A+B$ 的正定

(ii) 举例说明 AB 不一定对称.

(iii) 证明 AB 相似于正定矩阵.

Pf (i) $\because A$ 正定 $\therefore \exists$ 可逆矩阵 $P \in GL_n(\mathbb{R})$ s.t. $A = P^t P$

$$\text{则 } A^2 = (P^t P) \cdot (P^t P) \Leftrightarrow Q = P^t P \text{ 为 } P \text{ 可逆} \therefore Q \text{ 可逆 且 } A^2 = Q^t \cdot Q$$

$\therefore A^2$ 正定

$\because A, B$ 正定 $\therefore \forall \vec{x} \in \mathbb{R}^n \setminus \{\vec{0}\}$ $\vec{x}^t A \vec{x} > 0, \vec{x}^t B \vec{x} > 0$

$\therefore \vec{x}^t (A+B) \vec{x} = \vec{x}^t A \vec{x} + \vec{x}^t B \vec{x} > 0 \Rightarrow A+B$ 正定.

(ii) $A = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}, B = \begin{pmatrix} 1 & 1 \\ 1 & 3 \end{pmatrix} \Rightarrow A \cdot B = \begin{pmatrix} 2 & 4 \\ 3 & 7 \end{pmatrix}$ 不对称.

(iii) $\because A, B$ 正定 $\therefore \exists$ 可逆矩阵 $P_1, P_2 \in GL_n(\mathbb{R})$ s.t. $A = P_1^t P_1, B = P_2^t P_2$

$$\text{则 } (P_1^t)^{-1} \cdot (AB) \cdot P_1^t = (P_1^t)^{-1} \cdot P_1^t P_1 \cdot P_2^t \cdot P_2 \cdot P_1^t = P_1 P_1^t P_2 P_2^t = (P_2 P_1^t)^t \cdot (P_2 P_1^t)$$

$\therefore Q = P_2 P_1^t \quad \because P_1, P_2 \in GL_n(\mathbb{R}) \quad \therefore Q \in GL_n(\mathbb{R}) \quad \therefore Q^t Q$ 是正定矩阵

即 \exists 可逆矩阵 P_1^t s.t. $(P_1^t)^{-1} \cdot (AB) \cdot P_1^t = Q^t \cdot Q \Rightarrow AB$ 相似于正定矩阵.

8. $A \in SM_n(\mathbb{R})$ 正定. 定义 $q: \mathbb{R}^n \rightarrow \mathbb{R}$

$$\begin{pmatrix} \vec{x} \\ \vdots \\ \vec{x} \end{pmatrix} \mapsto \det \begin{pmatrix} A & \vec{x} \\ \vec{x}^t & 0 \end{pmatrix}$$

(i) 证明: q 是 \mathbb{R}^n 上二次型

(ii) 证明: q 为实数

$$\text{Pf. } q(-\vec{x}) = \det \begin{pmatrix} A & -\vec{x} \\ -\vec{x}^t & 0 \end{pmatrix} = -\det \begin{pmatrix} A & \vec{x} \\ \vec{x}^t & 0 \end{pmatrix} = \det \begin{pmatrix} A & \vec{x} \\ \vec{x}^t & 0 \end{pmatrix} = q(\vec{x})$$

$$\text{设 } f(x, y) = \frac{1}{2} [q(\vec{x} + \vec{y}) - q(\vec{x}) - q(\vec{y})]$$

$$\begin{aligned}
& \text{证 } f(x, y) = \frac{1}{2} [\det \begin{pmatrix} A & (\vec{x} + \vec{y}) \\ (\vec{x} + \vec{y})^t & 0 \end{pmatrix} - \det \begin{pmatrix} A & \vec{x} \\ \vec{x}^t & 0 \end{pmatrix} - \det \begin{pmatrix} A & \vec{y} \\ \vec{y}^t & 0 \end{pmatrix}] \\
&= \frac{1}{2} [\det \begin{pmatrix} A & \vec{x} \\ \vec{x}^t + \vec{y}^t & 0 \end{pmatrix} + \det \begin{pmatrix} A & \vec{y} \\ \vec{x}^t + \vec{y}^t & 0 \end{pmatrix} - \det \begin{pmatrix} A & \vec{x} \\ \vec{x}^t & 0 \end{pmatrix} - \det \begin{pmatrix} A & \vec{y} \\ \vec{y}^t & 0 \end{pmatrix}] \\
&= \frac{1}{2} [\det \begin{pmatrix} A & \vec{x} \\ \vec{y}^t & 0 \end{pmatrix} + \det \begin{pmatrix} A & \vec{y} \\ \vec{x}^t & 0 \end{pmatrix}]
\end{aligned}$$

$\forall \alpha, \beta \in \mathbb{R}, \vec{x}_1, \vec{x}_2, \vec{y}_1, \vec{y}_2 \in \mathbb{R}^n \quad \text{则:}$

$$\begin{aligned}
f(\alpha \vec{x}_1 + \beta \vec{x}_2, \vec{y}_1) &= \frac{1}{2} [\det \begin{pmatrix} A & \alpha \vec{x}_1 + \beta \vec{x}_2 \\ \vec{y}_1^t & 0 \end{pmatrix} + \det \begin{pmatrix} A & \vec{y}_1 \\ \alpha \vec{x}_1^t + \beta \vec{x}_2^t & 0 \end{pmatrix}] \\
&= \frac{1}{2} [\alpha \det \begin{pmatrix} A & \vec{x}_1 \\ \vec{y}_1^t & 0 \end{pmatrix} + \beta \det \begin{pmatrix} A & \vec{x}_2 \\ \vec{y}_1^t & 0 \end{pmatrix} + \alpha \det \begin{pmatrix} A & \vec{y}_1 \\ \vec{x}_1^t & 0 \end{pmatrix} + \beta \det \begin{pmatrix} A & \vec{y}_1 \\ \vec{x}_2^t & 0 \end{pmatrix}] \\
&= \alpha \frac{1}{2} [\det \begin{pmatrix} A & \vec{x}_1 \\ \vec{y}_1^t & 0 \end{pmatrix} + \det \begin{pmatrix} A & \vec{y}_1 \\ \vec{x}_1^t & 0 \end{pmatrix}] + \beta \cdot \frac{1}{2} [\det \begin{pmatrix} A & \vec{x}_2 \\ \vec{y}_1^t & 0 \end{pmatrix} + \det \begin{pmatrix} A & \vec{y}_1 \\ \vec{x}_2^t & 0 \end{pmatrix}] \\
&= \alpha f(\vec{x}_1, \vec{y}_1) + \beta f(\vec{x}_2, \vec{y}_1)
\end{aligned}$$

同理可证 $f(\vec{x}_1, \alpha \vec{x}_1 + \beta \vec{x}_2) = \alpha f(\vec{x}_1, \vec{y}_1) + \beta f(\vec{x}_1, \vec{y}_2)$

$\therefore f$ 是 \mathbb{R}^n 上的二次型 (对称) $\therefore q$ 是二次型.

$$\begin{aligned}
& \text{[证法]} \det \begin{pmatrix} A & \vec{x} \\ \vec{x}^t & 0 \end{pmatrix} = \det \begin{pmatrix} \vec{A}^{(1)} & \cdots & \vec{A}^{(n)} & \vec{x} \\ x_1 & \cdots & x_n & 0 \end{pmatrix} \xrightarrow{\text{按最后一列展开}} (-1)^{m_2} x_1 \det (\vec{A}^{(2)} \cdots \vec{A}^{(n)} \vec{x}) \\
& + \cdots + (-1)^{m_{n+1}} x_n \det (\vec{A}^{(1)} \cdots \vec{A}^{(n-1)} \vec{x}) \xrightarrow{\sum_{i=1}^n (-1)^{m_{n+i}} x_i \cdot \det (\vec{A}^{(1)} \cdots \vec{A}^{(n-1)} \vec{A}^{(n)} \cdots \vec{A}^{(n)} \vec{x})} \\
& \therefore \det (\vec{A}^{(1)} \cdots \vec{A}^{(n-1)} \vec{A}^{(n)} \cdots \vec{A}^{(n)} \vec{x}) \xrightarrow{\text{按最后一列展开}} (-1)^{n+1} x_1 \cdot M_{1,1} + \cdots + (-1)^{2n} x_n \cdot M_{n,n} \\
& \therefore \det \begin{pmatrix} A & \vec{x} \\ \vec{x}^t & 0 \end{pmatrix} = \sum_{i=1}^n (-1)^{n+i+1} x_i \cdot \left(\sum_{j=1}^n (-1)^{n+j} x_j M_{j,i} \right) \\
& = \sum_{i=1}^n \sum_{j=1}^n (-1)^{i+j+1} M_{j,i} \cdot x_i x_j \quad \text{是二次齐次多项式}
\end{aligned}$$

(其中 $M_{j,i}$ 为 A 去掉 j 行 i 列 n 行列式 \rightarrow 余子式) $\therefore q$ 是二次型.

(ii) $\because A$ 正定 $\therefore \exists$ 可逆矩阵 $P \in GL_n(\mathbb{R})$ st. $P^t A P = E_n$

$$\therefore Q = \begin{pmatrix} P & \vec{0} \\ \vec{x}^t & 1 \end{pmatrix} \quad \text{且} \quad B = Q^t \begin{pmatrix} A & \vec{x} \\ \vec{x}^t & 0 \end{pmatrix} Q$$

$$\text{① } B = \begin{pmatrix} P^t & \\ & 1 \end{pmatrix} \begin{pmatrix} A & \vec{x} \\ \vec{x}^t & 0 \end{pmatrix} \begin{pmatrix} P & \\ & 1 \end{pmatrix} = \begin{pmatrix} E_n & P^t \vec{x} \\ \vec{x}^t P & 0 \end{pmatrix}$$

$$\therefore \vec{y} = P^t \vec{x} \quad \text{则} \quad |B| = \begin{vmatrix} E_n & \vec{y} \\ \vec{y}^t & 0 \end{vmatrix} = \begin{vmatrix} 1 & \cdots & 1 & y_1 \\ & \ddots & & \vdots \\ & & 1 & y_n \\ y_1 & \cdots & y_n & 0 \end{vmatrix} = \begin{vmatrix} 1 & \cdots & 1 & y_1 \\ & \ddots & & \vdots \\ & & 1 & y_n \\ 0 & \cdots & 0 & -y_1^2 - \cdots - y_n^2 \end{vmatrix}$$

$$= -y_1^2 - \cdots - y_n^2$$

$$\text{而 } |B| = |Q^t| \cdot q(\vec{x}) \cdot |Q| = |Q|^2 \cdot q(\vec{x})$$

$$\therefore \forall \vec{x} \in \mathbb{R}^n \setminus \{0\} \quad q(\vec{x}) = \frac{|B|}{|Q|^2} < 0 \quad (\because \vec{x} \neq \vec{0} \therefore \vec{y} \neq \vec{0})$$

$\therefore q$ 负定.

$$\text{另求 (i)} \quad \begin{pmatrix} E_n & \vec{0} \\ -\vec{x}^t A^{-1} & 1 \end{pmatrix} \cdot \begin{pmatrix} A & \vec{x} \\ \vec{x}^t & 0 \end{pmatrix} = \begin{pmatrix} A & \vec{x} \\ 0 & -\vec{x}^t A^{-1} \vec{x} \end{pmatrix}$$

$$\therefore q(\vec{x}) = \det \begin{pmatrix} A & \vec{x} \\ \vec{x}^t & 0 \end{pmatrix} = \det \left[\begin{pmatrix} E_n & \vec{0} \\ -\vec{x}^t A^{-1} & 1 \end{pmatrix} \cdot \begin{pmatrix} A & \vec{x} \\ \vec{x}^t & 0 \end{pmatrix} \right]$$

$$= \det \begin{pmatrix} A & \vec{x} \\ 0 & -\vec{x}^t A^{-1} \vec{x} \end{pmatrix} = -|A| \cdot (-\vec{x}^t A^{-1} \vec{x})$$

$$\therefore q \text{ 为二次型 且 } \because A \text{ 正定 } \therefore A^{-1} \text{ 正定 且 } -|A| < 0$$

(iii) $\therefore q$ 为负定 = 二次型.